



PHYSICS AND ENGINEERING PHYSICS

SuperDARN Pulse Sequences - Optimization and Testing -

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Outline

- ACF introduction and theory.
- FITACF:
 - Theory; known pitfalls; data examples
- [Why] do we need a new pulse sequence?
- The new sequences.
- Data examples.
- Statistics.



Multi-Pulse Theory...

- SuperDARN transmitters send out a series of pulses, which are sampled by the receivers.
- Measure the power and phase of the signal scattered back to the radar from each distance along the beam.
- Determine characteristics of the scattering plasma waves
 - power, velocity, spectral width



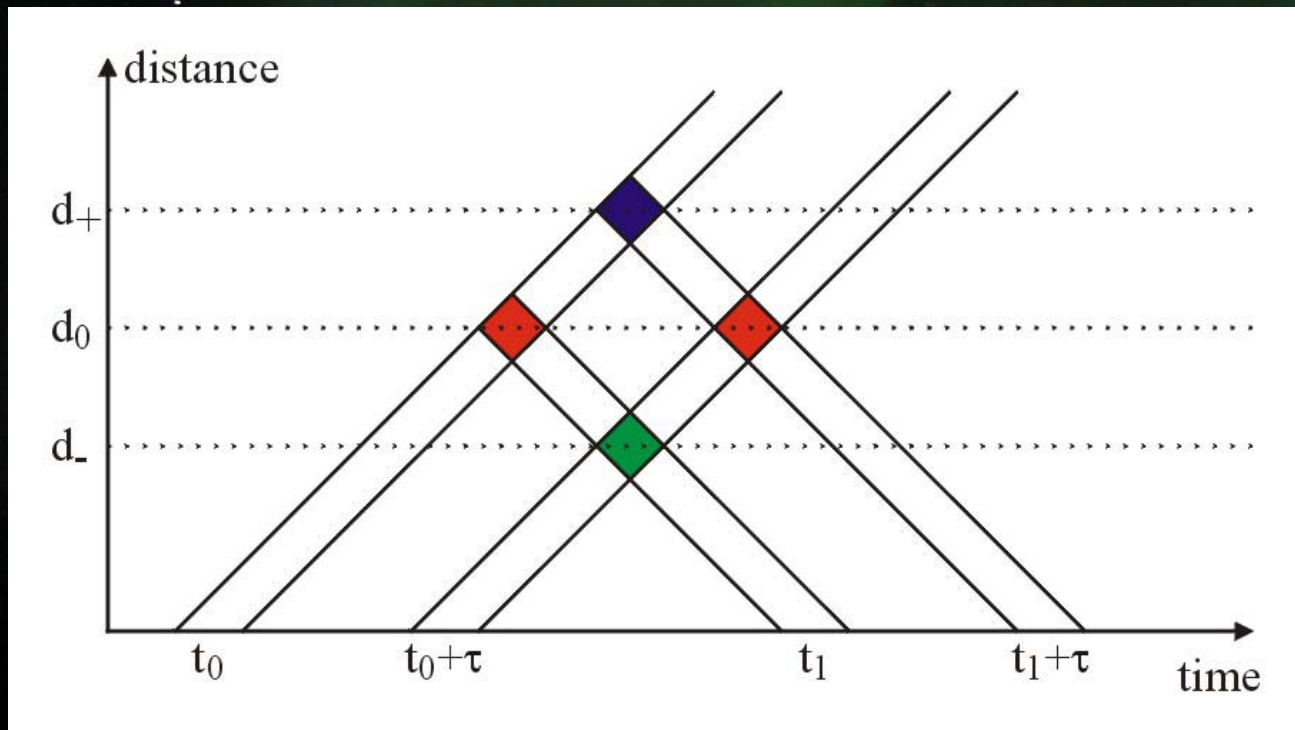
Multi-Pulse Reality...

- It isn't actually that simple. (of course!)
- How do we sort out the returns from different pulses and from different distances?
 - The answer: Complex autocorrelation functions (ACFs).
 - (Indeed!)



2-Pulse Sequence

- We want to know how much the plasma at distance d_0 has moved in time τ .
- We send out 2 pulses, separated by time τ .



2-Pulse Sequence

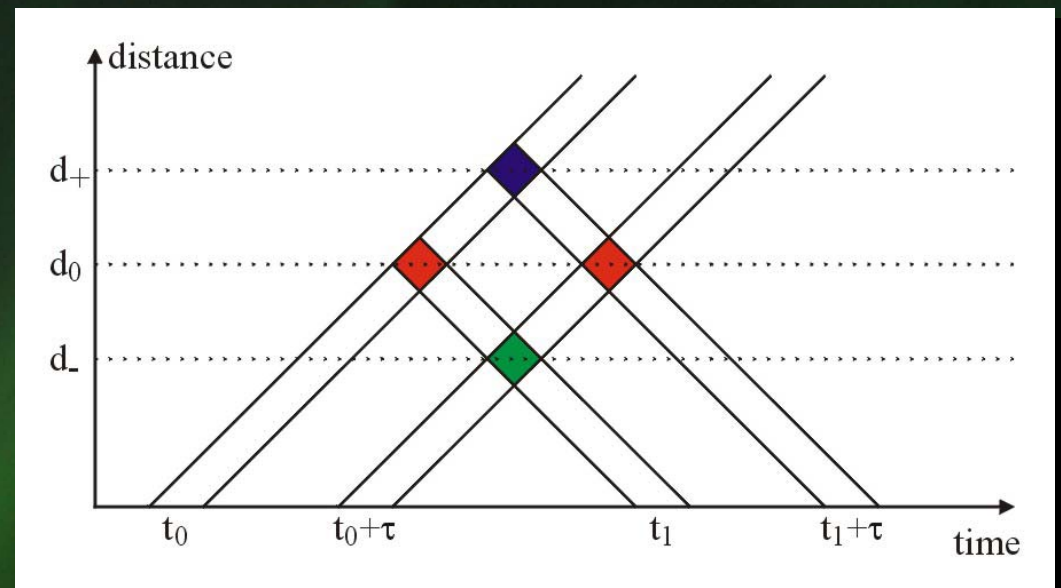
Transmitted pulses:

- p1 at time t_0
- p2 at time $t_0 + \tau$

(Note: $t_1 = t_0 + 2d_0/c$, etc.)

Received pulses:

- p1 from d_0 at time t_1
- p1 from d_+ at time $t_1 + \tau$
- p2 from d_- at time t_1
- p2 from d_0 at time $t_1 + \tau$



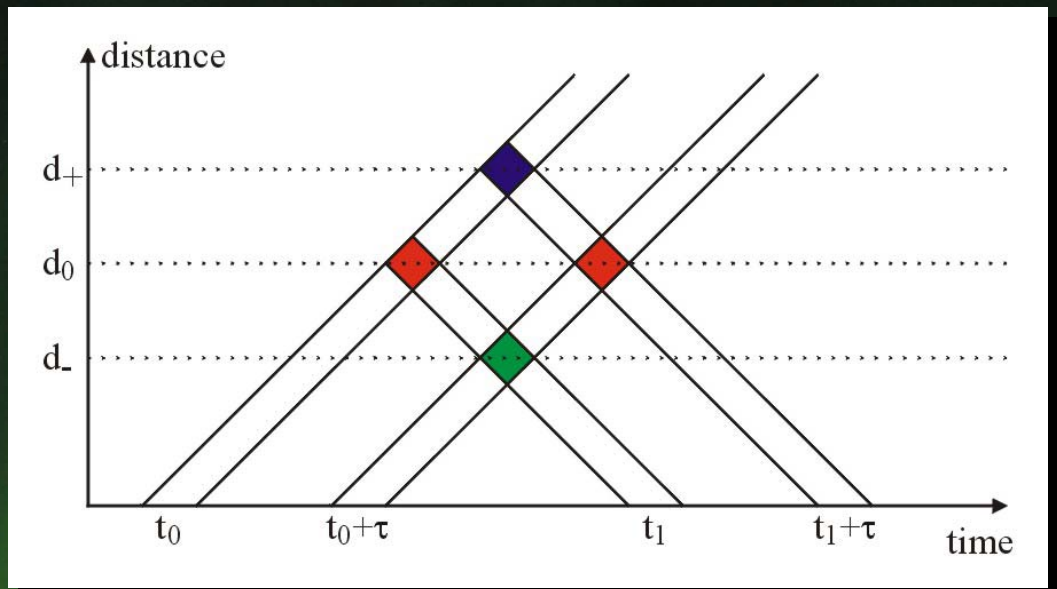
2-Pulse Sequence

Amplitude measured at t_1 :

$$A(t_1) = A_1(d_0) + A_2(d_-)$$

Amplitude measured at $t_1 + \tau$:

$$A(t_1 + \tau) = A_1(d_+) + A_2(d_0)$$



ACF at lag τ :

$$A(t_1) \cdot A(t_1 + \tau) = (A_1(d_0) + A_2(d_-)) \cdot (A_1(d_+) + A_2(d_0))$$

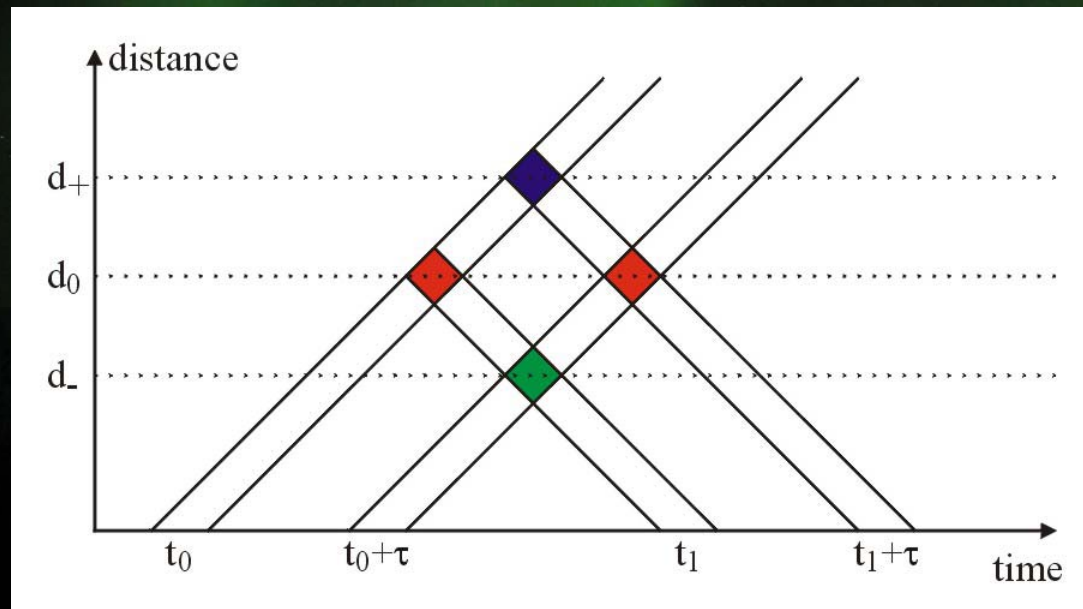


ACF at lag τ

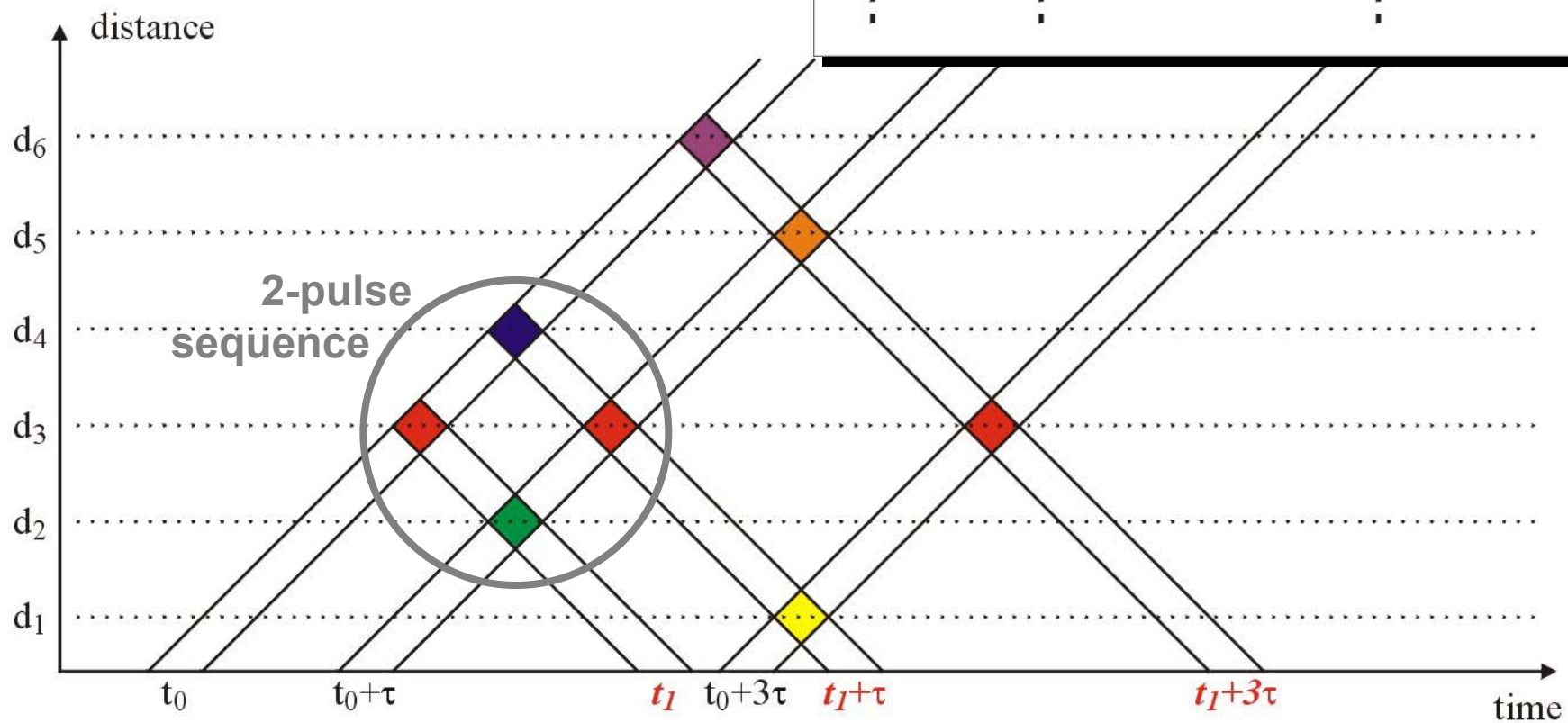
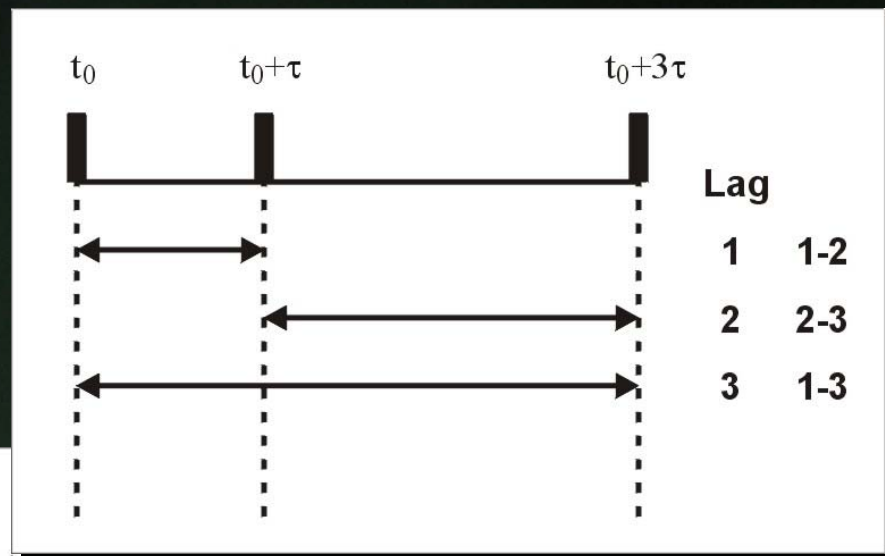
$$\langle A(t_1) \cdot A(t_1 + \tau) \rangle = \langle A_1(d_0) \cdot A_2(d_0) \rangle + \langle A_1(d_0) \cdot A_1(d_+) \rangle + \langle A_2(d_-) \cdot A_1(d_+) \rangle + \langle A_2(d_-) \cdot A_2(d_0) \rangle$$

- Average several return signals to minimize uncorrelated signal (phases) from different ranges ($\langle \rangle$).
- This works if ionosphere correlated at d_0 over averaging time

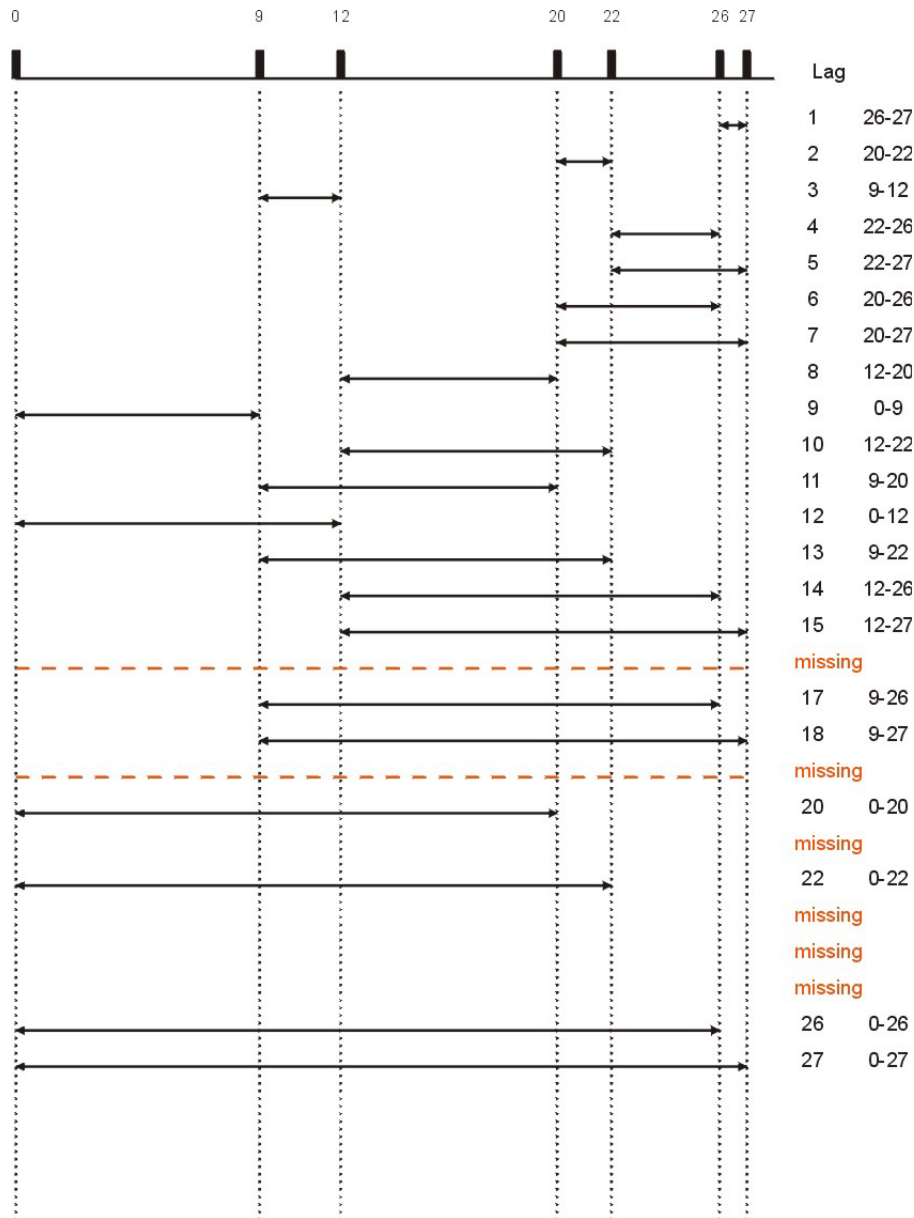
$$\langle A(t_1) \cdot A(t_1 + \tau) \rangle \sim \langle A_1(d_0) \cdot A_2(d_0) \rangle \sim A e^{i\omega\tau}$$



3-Pulse Sequence



[0, 9, 12, 20, 22, 26, 27]

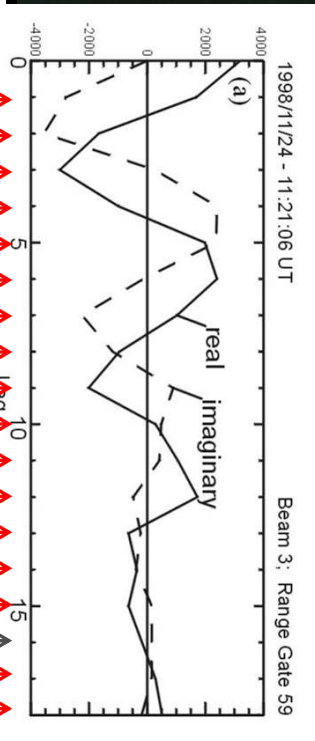
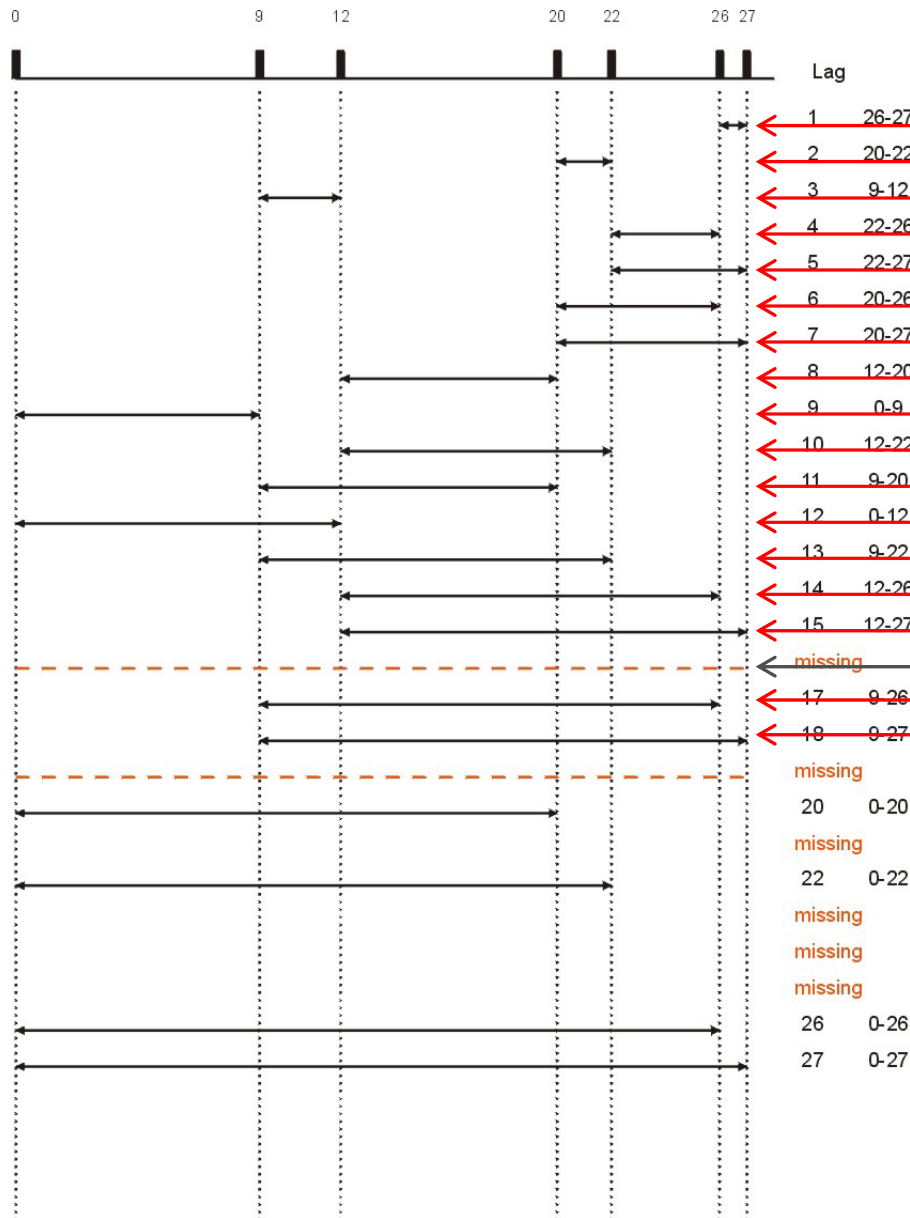


Current SuperDARN Pulse Sequence

- 7 pulses
- 2.4 ms τ
- .3 ms pulse length (45 km range gate)
- no repeated lags
- first missing lags at 16τ and 19τ
- by Schiffler



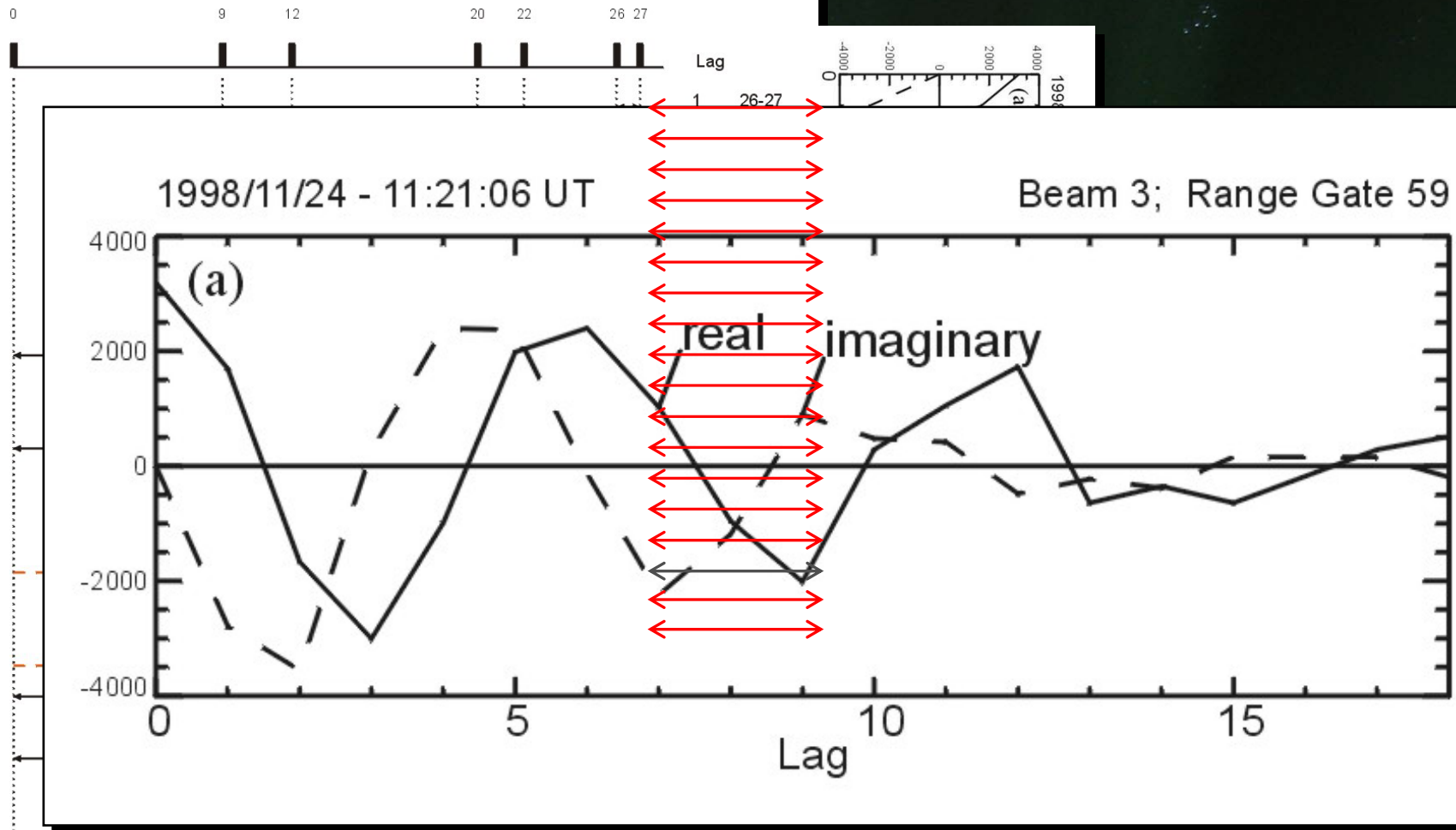
[0, 9, 12, 20, 22, 26, 27]



How Do We
Get From a
Lag Table
to an ACF?



[0, 9, 12, 20, 22, 26, 27]



missing

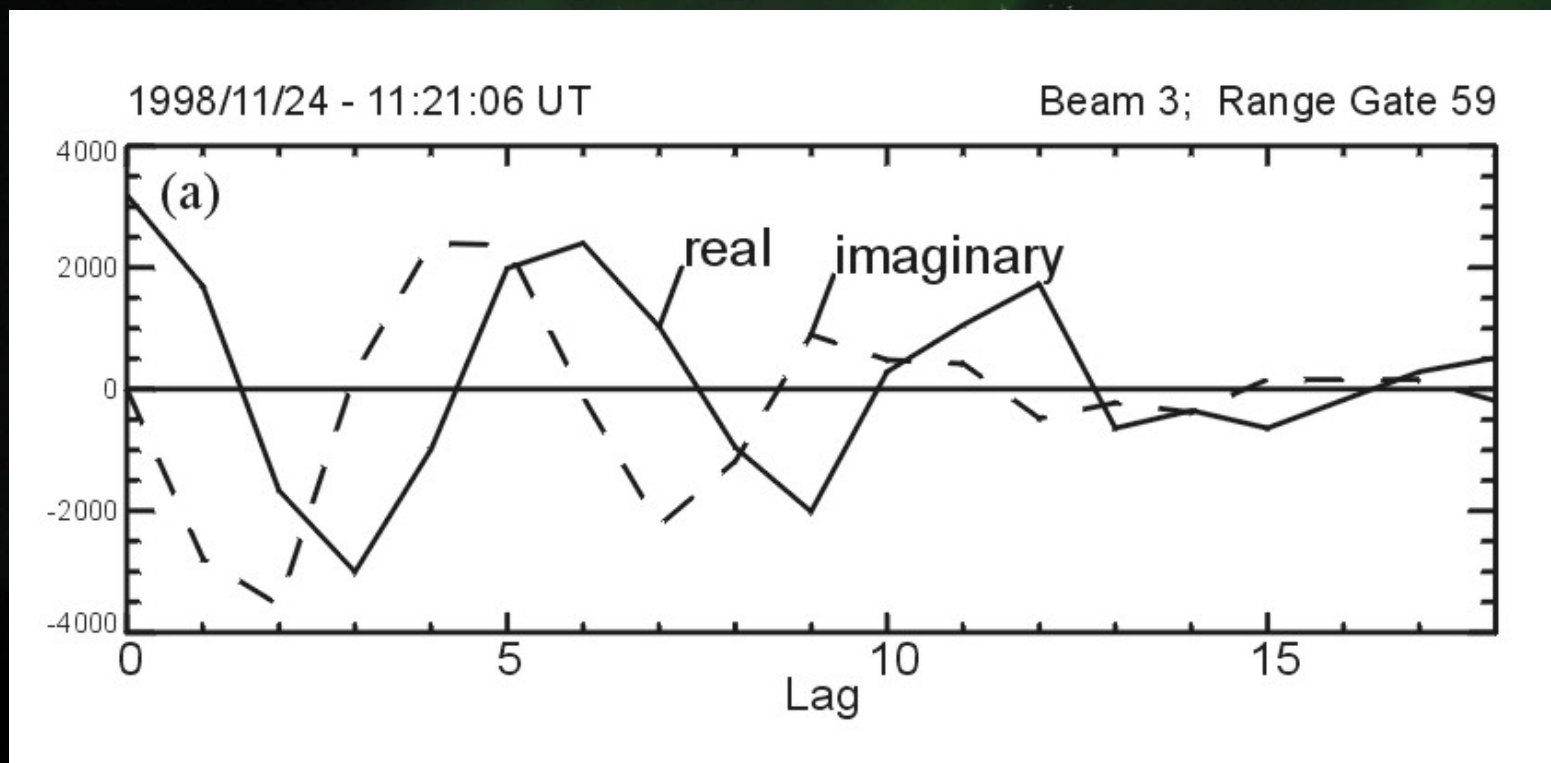
26	0-26
27	0-27



What the Radars Measure

- What's in a .dat file? -

Real and imaginary contribution for each lag.
(in phase & quadrature voltages)



FITACF

- Fourier transform of ACF gives spectrum (Wiener-Khinchin theorem)

but ...

- FITACF estimates spectral parameters without Fourier transforming the ACF:
 - mean doppler velocity
 - spectral width
 - backscattered power

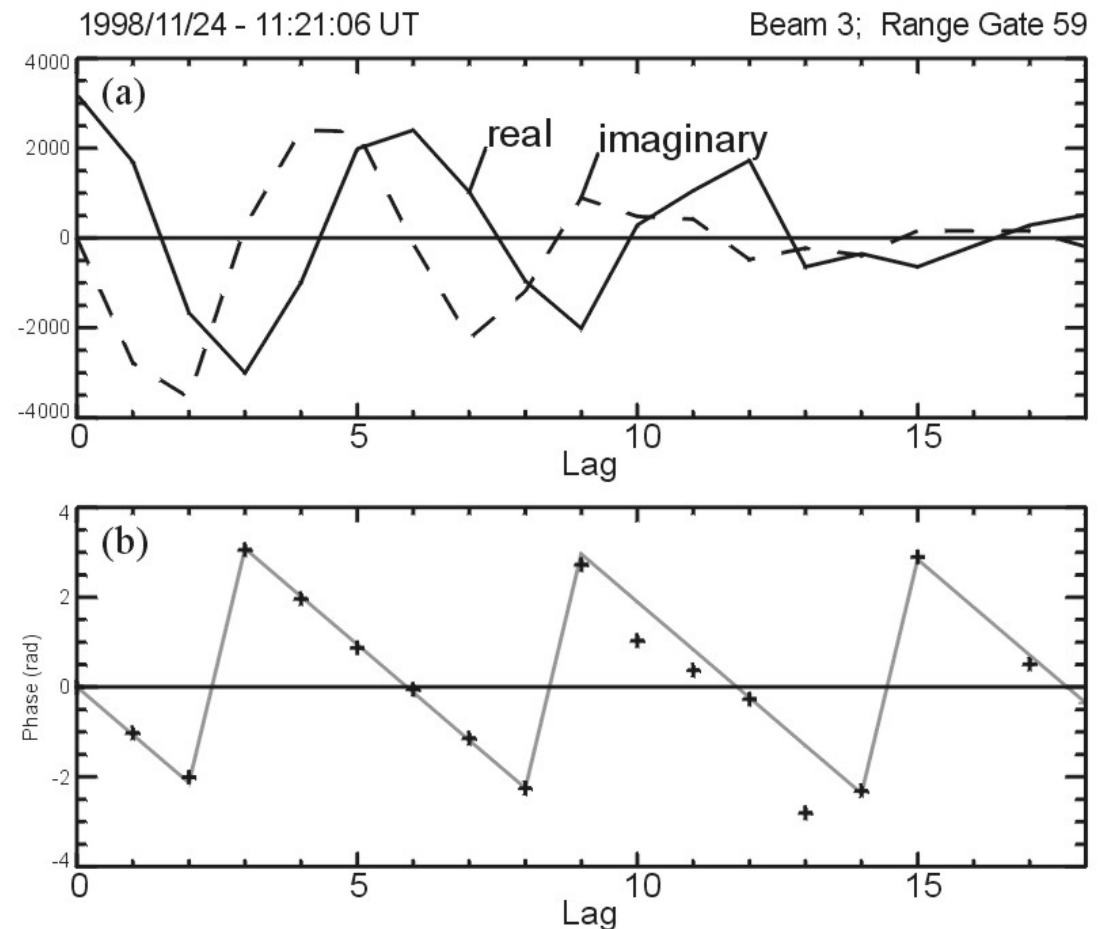


Φ - The Phase of the ACF

- ACF is of the form: $Ae^{i\Phi}$

$$\Phi = \text{atan}(\text{Im}/\text{Re})$$

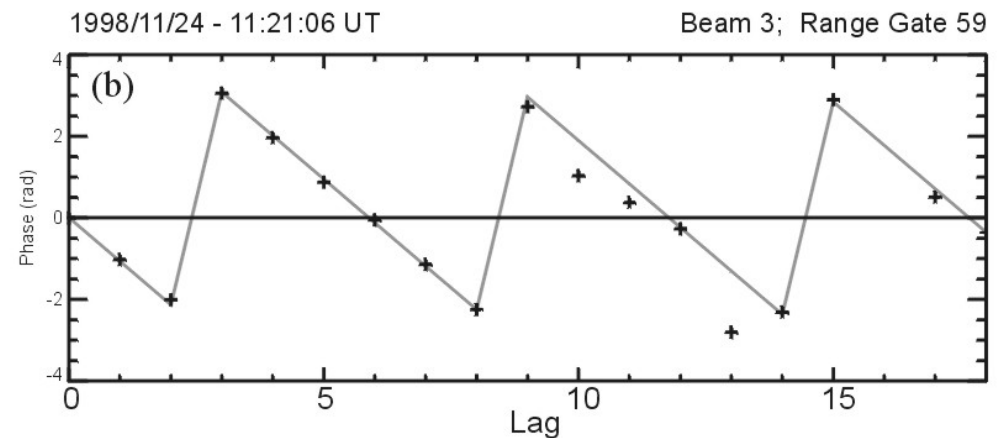
- phase varies linearly with lag between $\pm\pi$
- note 2π jumps



Getting Velocity from Φ

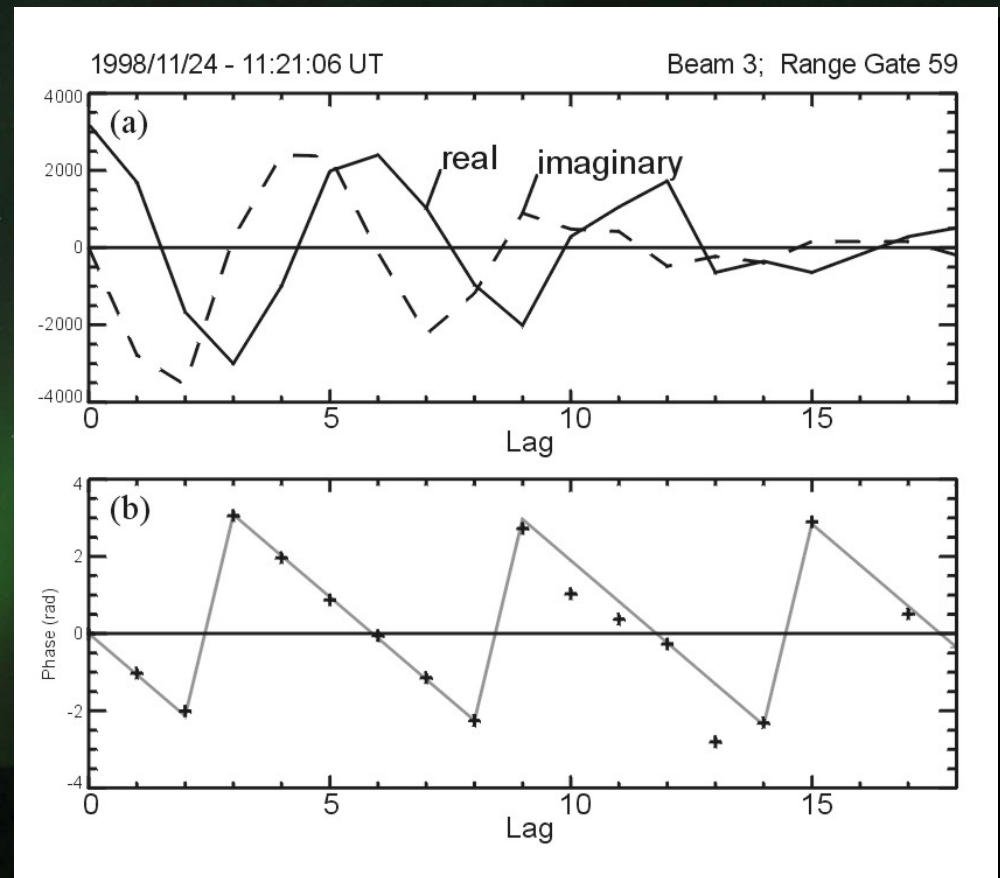
- If there is a dominant velocity (spectral peak) then doppler velocity $\langle \omega_D \rangle$ depends linearly on phase.
- Gain accuracy of vel. over Fourier method (sampling).

$$\Phi = \langle \omega_D \rangle k \tau,$$
$$\langle v_D \rangle = c \langle \omega_D \rangle / (4\pi f_{\text{radar}})$$



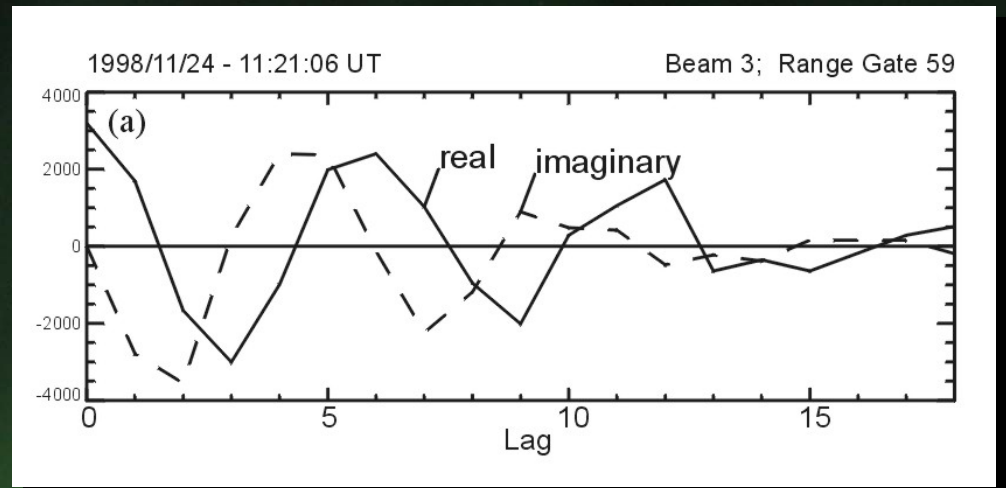
Decay of the ACF

- In nature, plasma structure in sampling volume changes with time.
- Over time, plasma is less well correlated.
- \therefore ACFs become less correlated with increasing lag.
- Manifested in decay of ACF envelope.



Spectral Width - Decay of the ACF

- Rate of decay of ACF determines the FITACF estimate of spectral width.
- Can be fitted with a Lorentzian or a Gaussian function:
 - *width_I*
 - *width_s*



$$\Delta\nu = 2\beta c / (4\pi f_{\text{radar}})$$

For a Lorentzian fit the characteristic decay $1/\beta$ is related to spectral width $\Delta\nu$.



Backscattered Power

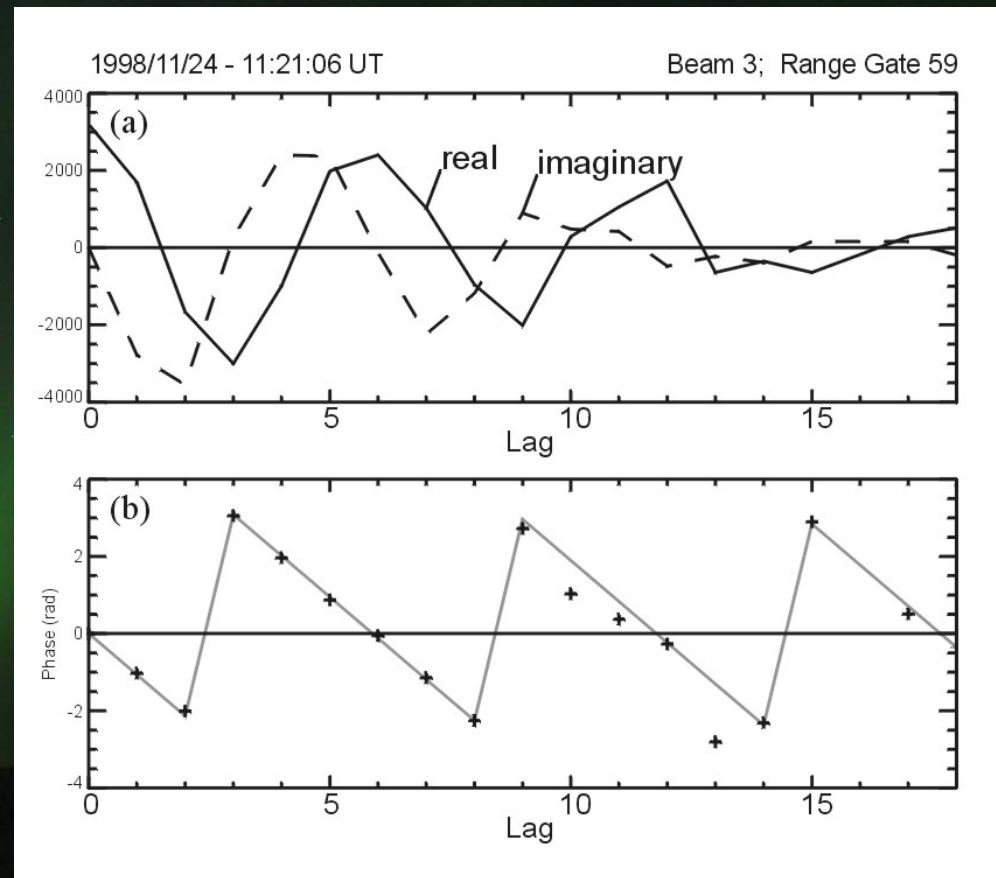
- Measured power at lag 0 (where $\text{Im}=0$) is related to spectral power:

- *pwr_0*

- The value of fitted ACF (Lorentzian or Gaussian) at lag 0 gives fitted backscattered power:

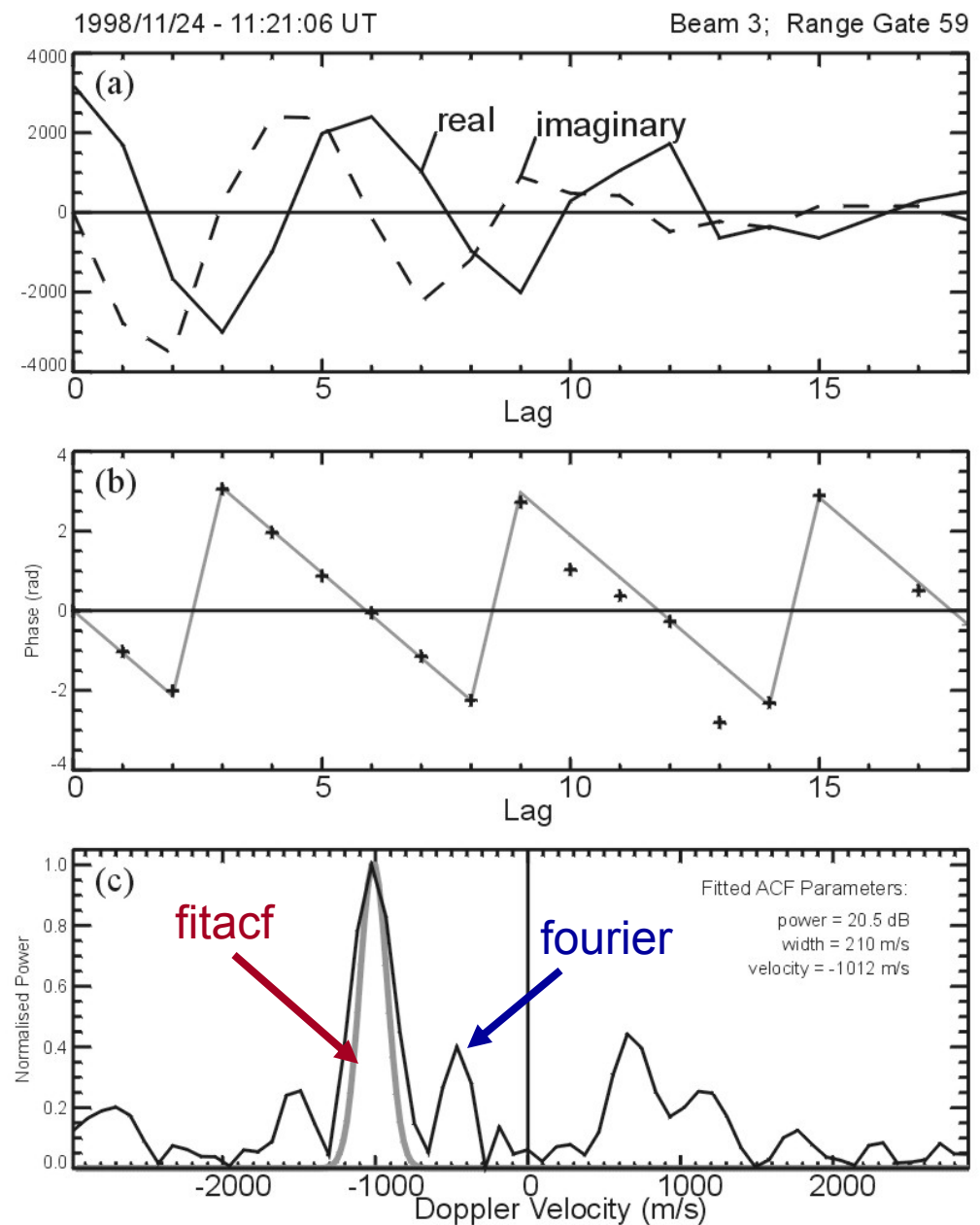
- *pwr_l*

- *pwr_s*



What's in a .fit file:

- Fitted values of velocity, power, and width, defining fitted spectrum.
- For single-peaked spectra this is very good!
- (Recall that Fourier transform of ACF gives actual spectrum.)



What's in a .fit file?

- Summary -

- Backscattered Power:
 - Lag 0 power (fitted*)
- Doppler Velocity:
 - Rate of change of ACF phase, $\Phi = \langle \omega_D \rangle k\tau$ ($k \in \mathfrak{Z}$)
 - $\langle v_D \rangle = c \langle \omega_D \rangle / (4\pi f_{\text{radar}})$
- Spectral Width:
 - Rate of decay of ACF envelope (fitted)



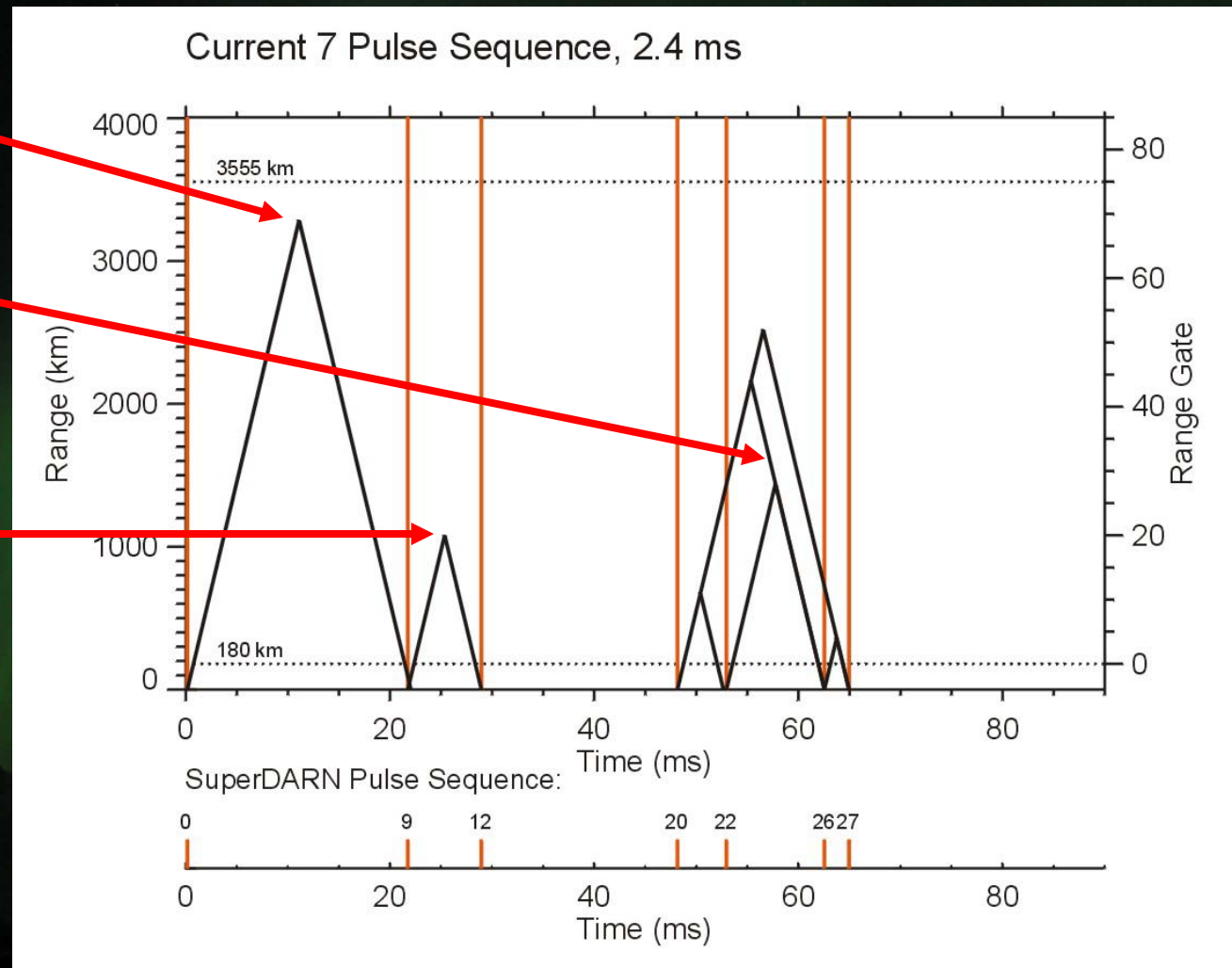
Pitfalls and Bad Lags

- In all cases, can **NOT** receive when Tx on.
- Often, ACFs are bad when no Lag 0.
 - Must not be transmitting when receiving first echoes from a pulse (Lag 0).
- First few lags crucial to ACF fitting technique.
- Cross-range noise:
 - Self-correlated echoes come from 2 different ranges at the same time.
 - Compare Lag 0 power at possible ranges. If power is much stronger in one range gate, then dominant signal assumed to be from there.



Tx On & Cross-Range Noise

- no lag 0 power
- cross-range noise ex.
- (note that lag 3 returns from RG~20 when Tx on)



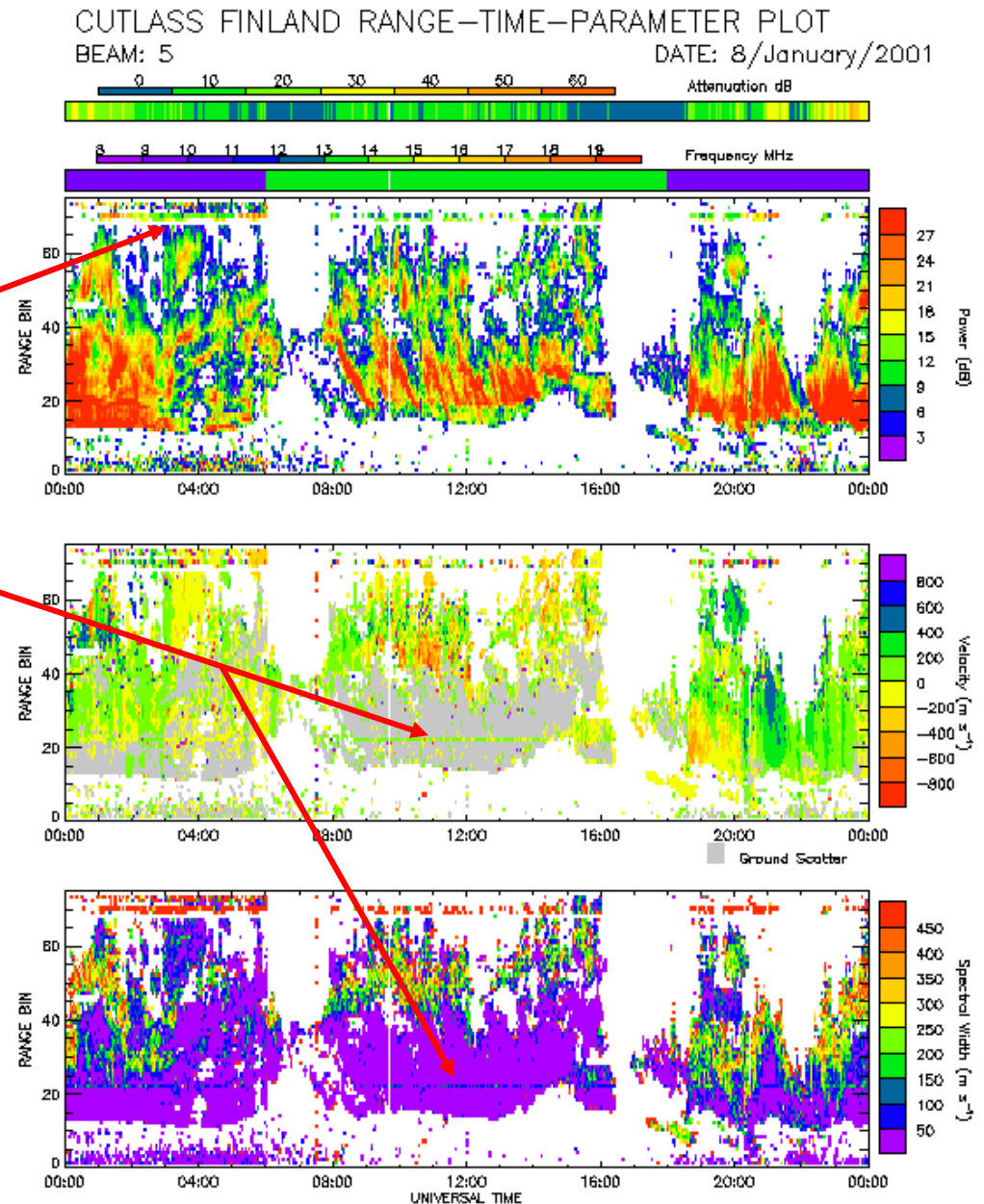
Pitfalls and Bad Lags

- In general, data disregarded if:
 - Rx off due to Tx on
 - Power is similar or weaker than simultaneous returns from another range gate
 - Unphysical ACF (often HF interference)



Bad Lags in Real Data

- RG 68 – missing Lag 0
– (Tx pulse 2; Rx pulse 1)
- RG 20 – Missing 3τ
– (Tx pulse 12; Rx pulse 9)
– Seems to be a critical lag; perhaps where ACF often has first 2π jump?
- probable cross-range noise at far ranges (only when lots of other scatter at near ranges)



Some Real ACFs – *High Velocity*

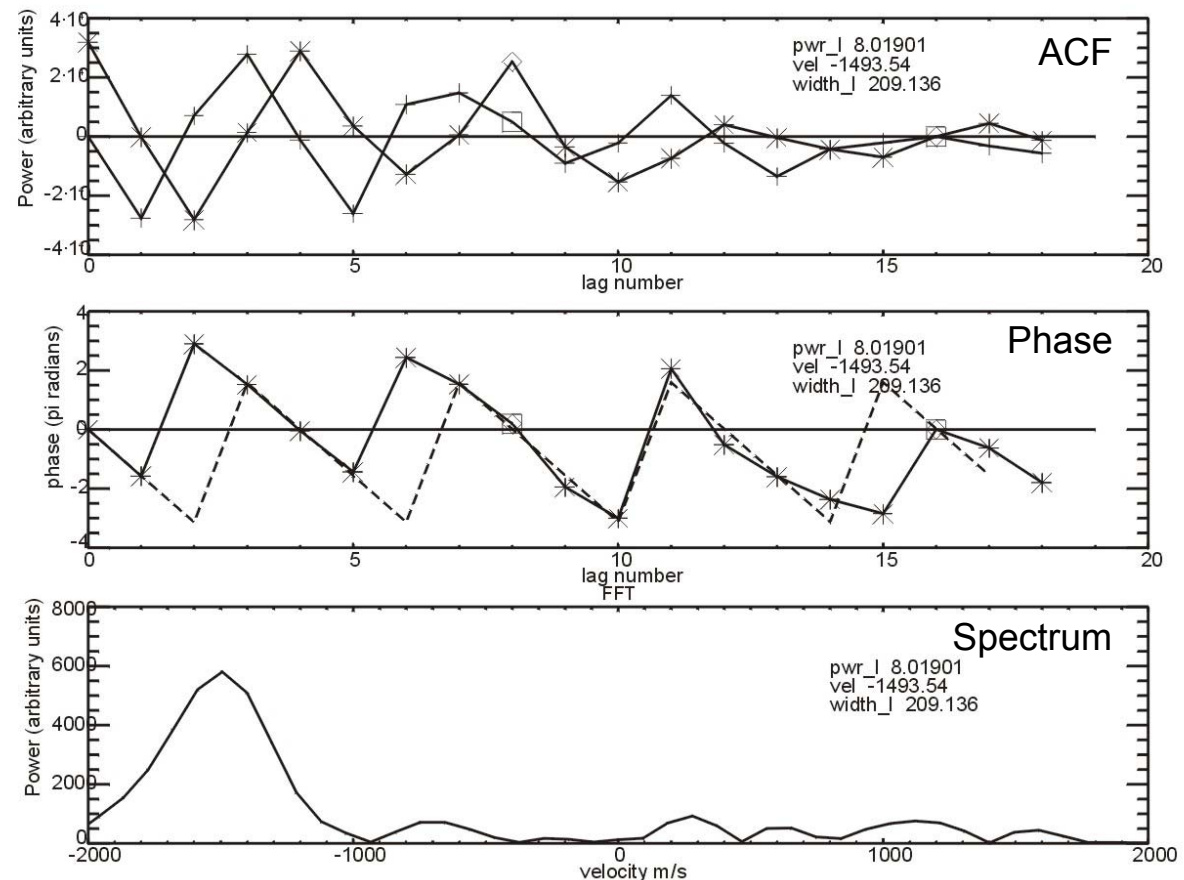
- rapid phase change
- moderate decay of ACF envelope
- fitted par's:
 - pwr = 8.0
 - vel = -1490
 - wid = 209

SuperDARN raw data plot

Kapuskasing: Beam=0, range=35, 04:21:47 UT

22 Dec 2002

unknown scan mode (-155)



Some Real ACFs – Low Velocity

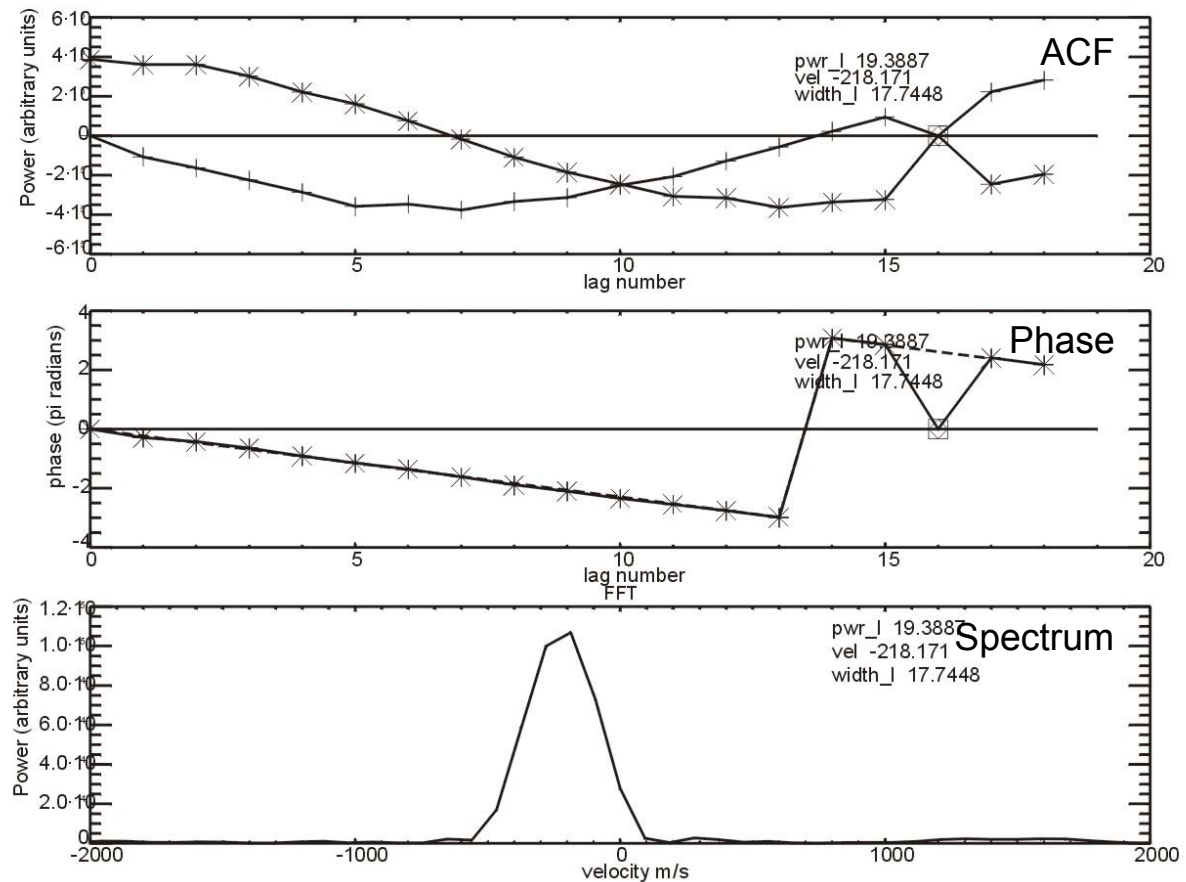
- slow phase change
- slower decay of ACF envelope
- fitted par's:
 - pwr = 19.4
 - vel = -218
 - wid = 17.7

SuperDARN raw data plot

Kapuskasing: Beam=0, range=18, 04:29:47 UT

22 Dec 2002

unknown scan mode (-155)



Some Real ACFs – Ground Scatter

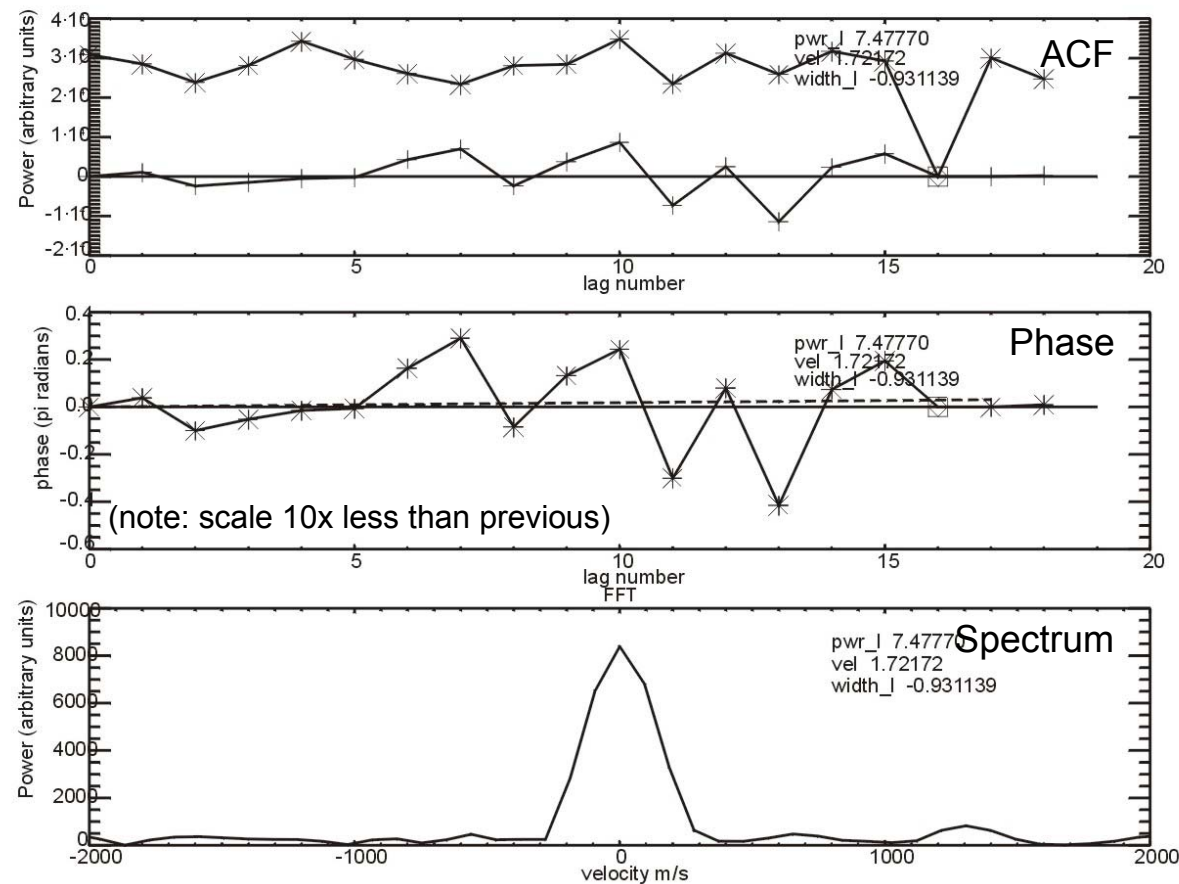
- basically no phase change (ground not moving!)
- no decay of ACF envelope (ground correlated!)
- possible real vel. imbedded
- fitted par's:
 - pwr = 7.5
 - vel = -1.7
 - wid = -0.9

SuperDARN raw data plot

Kapuskasing: Beam=0, range=54, 04:29:47 UT

22 Dec 2002

unknown scan mode (-155)



Some Real ACFs - Bad

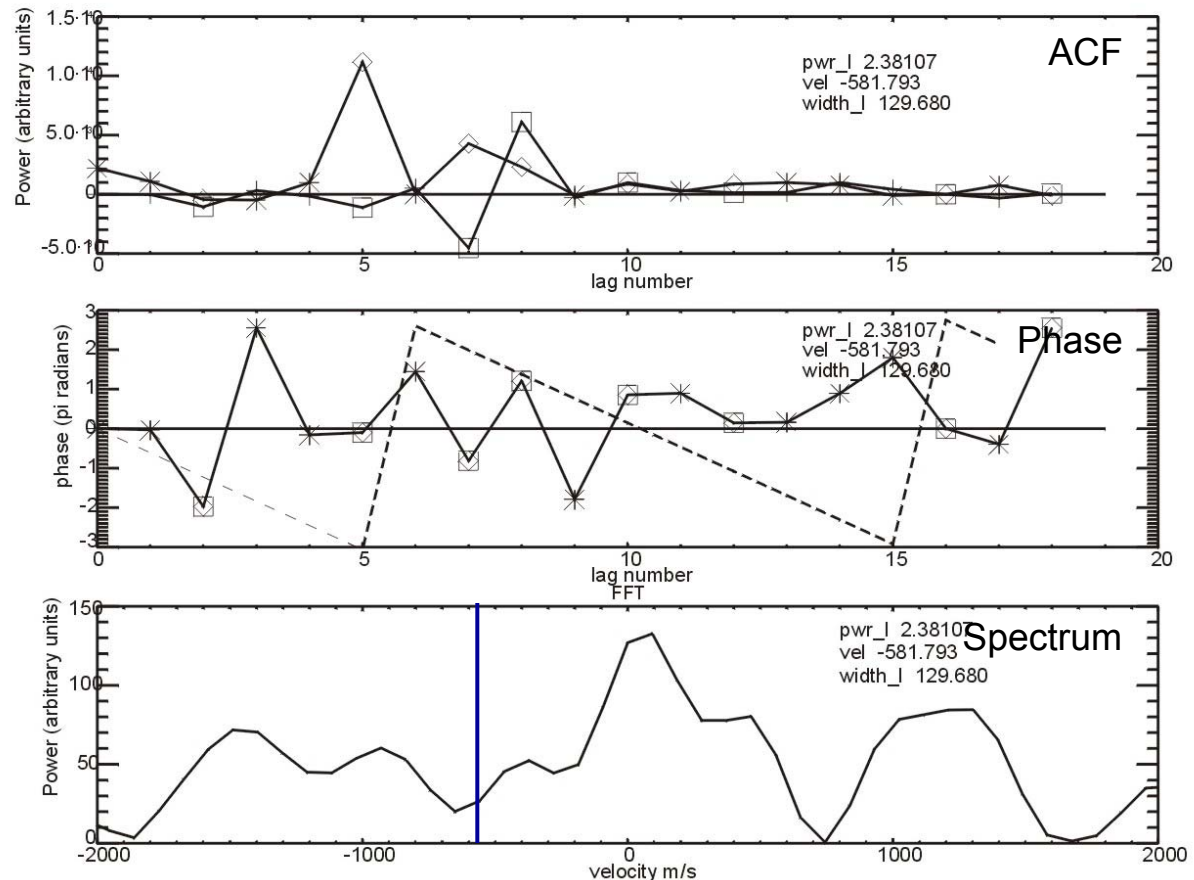
- low power
- bad linear fit to phase
- very poor ACF and spectrum
- fitted(!) par's:
 - $\text{pwr} = 2.4 \pm 1.9$ ($< 3\text{dB}$)
 - $\text{vel} = -582 \pm 170$
 - $\text{wid} = 130 \pm 140$

SuperDARN raw data plot

Kapuskasing: Beam=5, range=44, 04:03:12 UT

22 Dec 2002

unknown scan mode (-155)



So if it's already working, why would we want to change it?

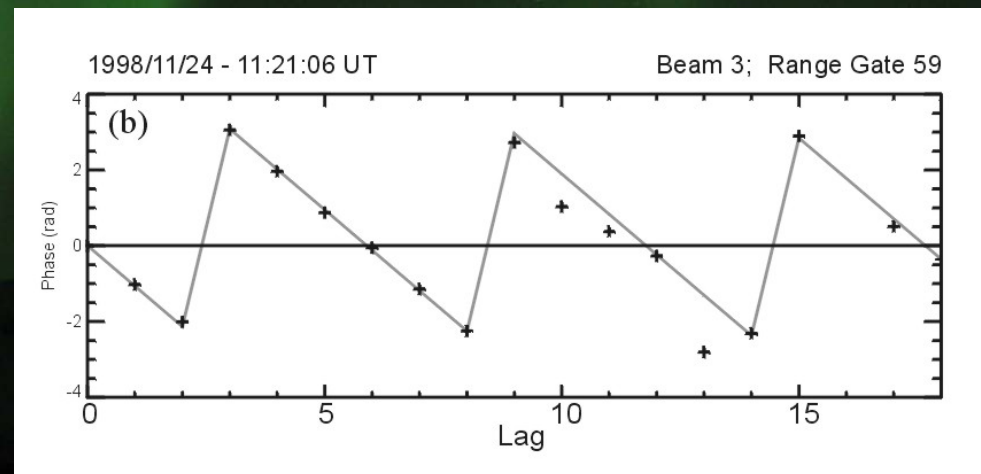
- Improve ACF accuracy
 - number of points in the ACF could be increased (decrease τ)
- Increase maximum (alias) velocity
 - determined by lag separation τ



Maximum ('Alias') Velocity

- Velocity determined from slope of ACF phase Φ , which varies between $\pm\pi$
- Therefore, $\omega_{\max} = \pi/\tau$

$$v_{\max} = c / (4\tau \cdot f_{\text{radar}})$$



Maximum ('alias') Velocity

Examples:

$$\tau=2.4 \text{ ms}; f_{\text{radar}}=18.0 \text{ MHz} \rightarrow v_{\text{alias}} = 1734 \text{ m/s}$$

$$\tau=2.4 \text{ ms}; f_{\text{radar}}=14.4 \text{ MHz} \rightarrow v_{\text{alias}} = 2170 \text{ m/s}$$

$$\tau=2.4 \text{ ms}; f_{\text{radar}}=10.2 \text{ MHz} \rightarrow v_{\text{alias}} = 3064 \text{ m/s}$$

$$\tau=1.5 \text{ ms}; f_{\text{radar}}=14.4 \text{ MHz} \rightarrow v_{\text{alias}} = 3470 \text{ m/s}$$

$$\tau=1.5 \text{ ms}; f_{\text{radar}}=10.2 \text{ MHz} \rightarrow v_{\text{alias}} = 4900 \text{ m/s}$$



Optimizing New Sequence

- No repeated lags.
- Minimize number of inherently missing lags.
- Long lag between first 2 pulses to get Lag 0 power at all ranges.
- Minimize τ to maximize number of points in ACF.
- Minimize missing lags due to Tx-on/Rx-off conflicts.

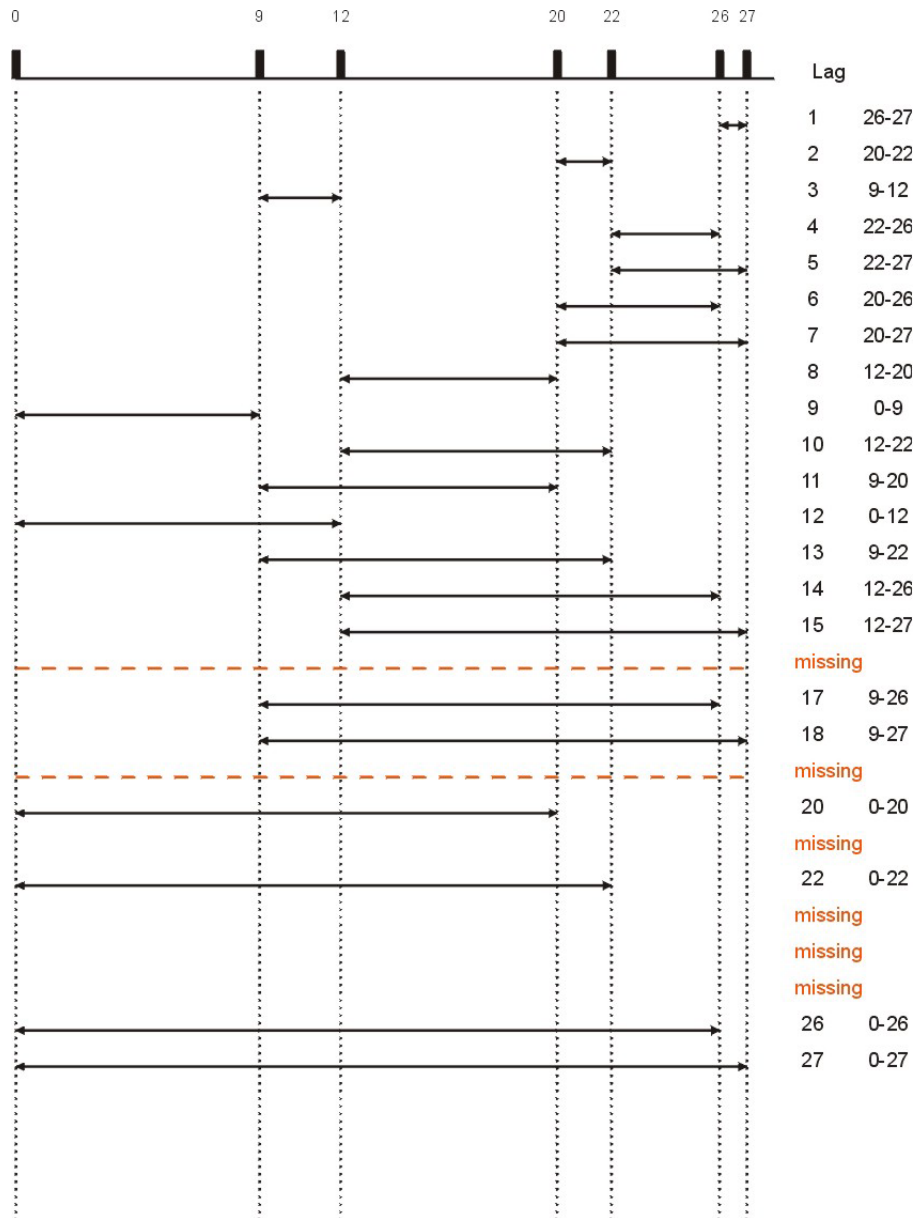


Tested Pulse Sequences

- Current 7-pulse:
 - [0, 9, 12, 20, 22, 26, 27], 2400 μs
- Ray's 8-pulse:
 - [0, 19, 28, 31, 39, 41, 45, 46], 1200 μs
- 'kat_scan' 8-pulse:
 - [0, 14, 22, 24, 27, 31, 42, 43], 1500 & 1800 μs
- 9-pulse:
 - [0, 16, 26, 27, 34, 46, 49, 51, 55], 1500 μs

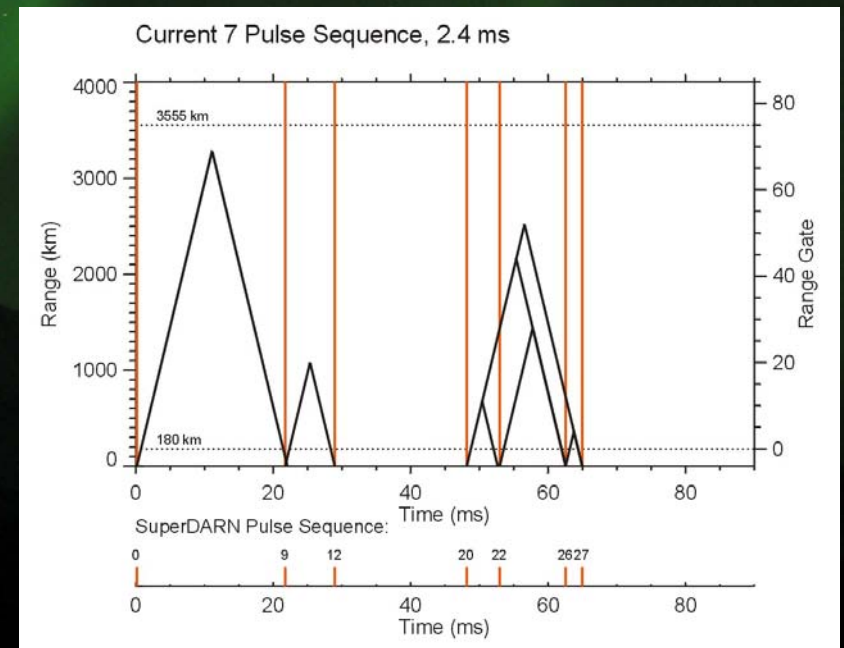


[0, 9, 12, 20, 22, 26, 27]

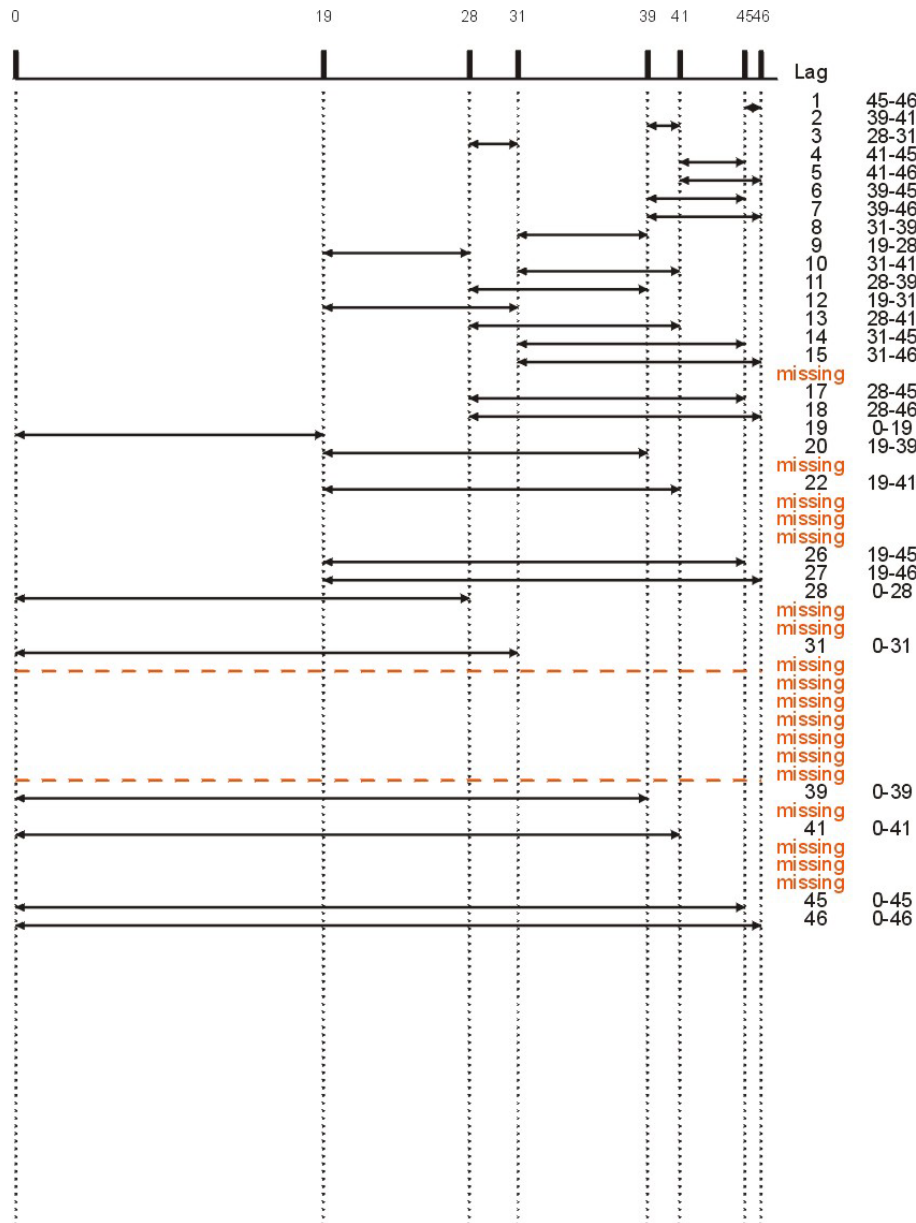


Current Sequence

- 7 pulses, $\tau = 2400 \mu\text{s}$
- first missing lags at 16τ and 19τ

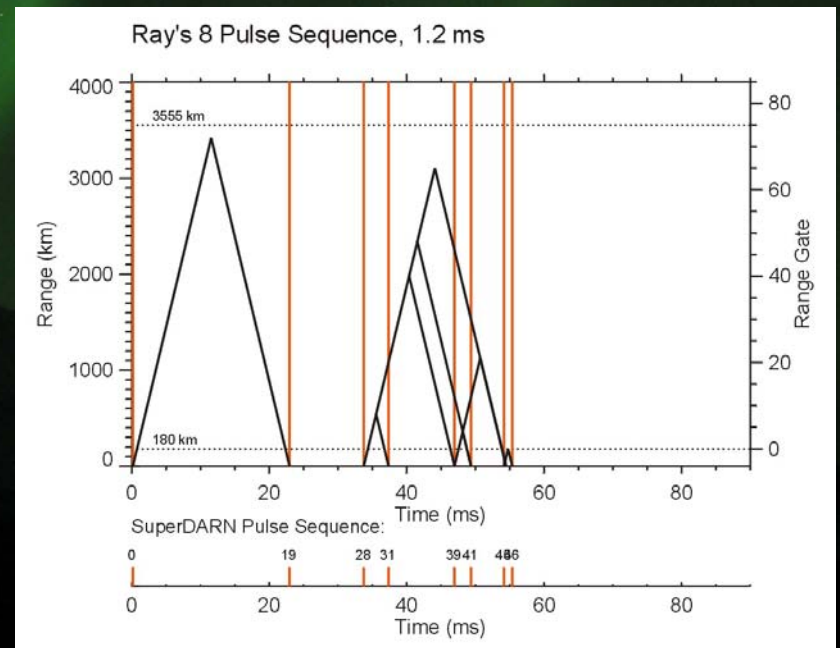


[0, 19, 28, 31, 39, 41, 45, 46]

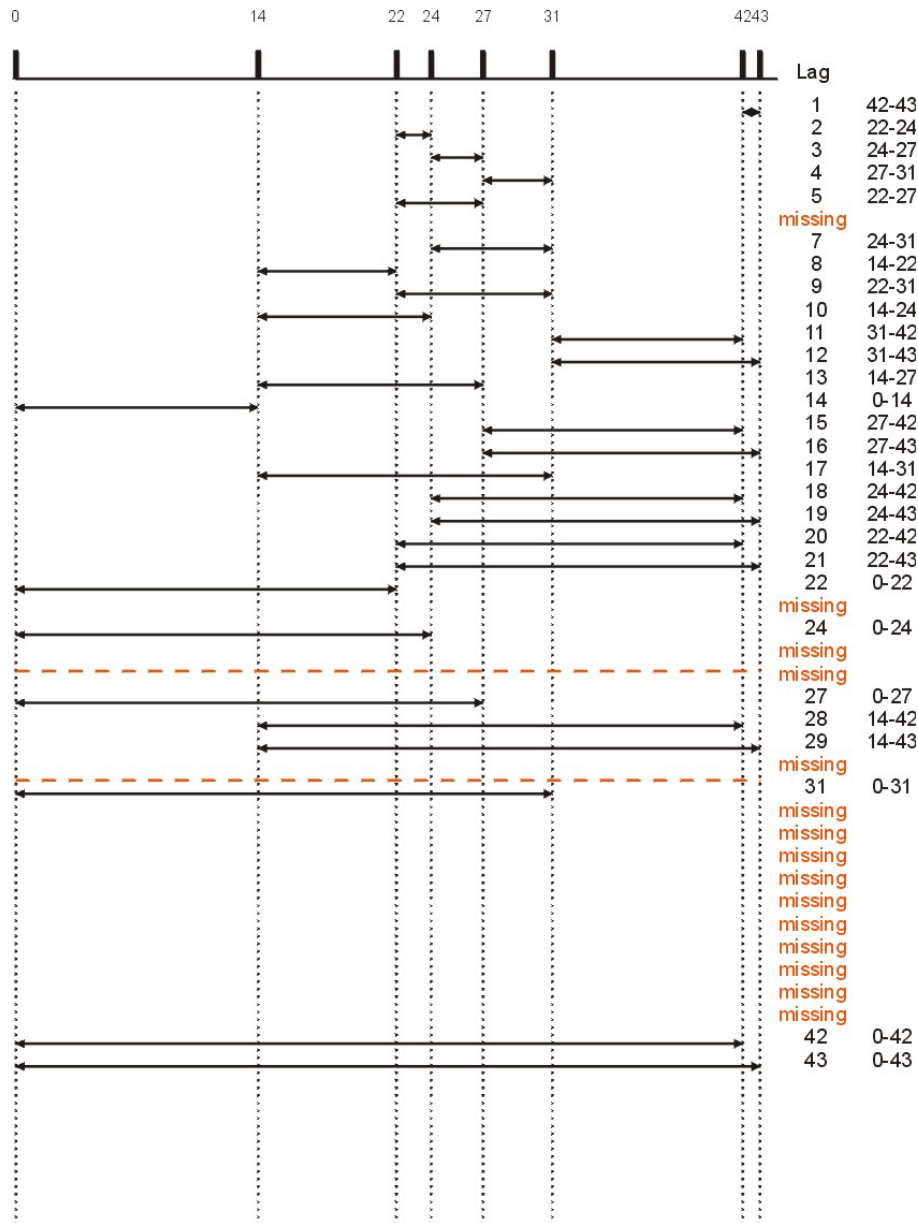


Ray's Sequence

- 8 pulses, $\tau = 1200 \mu\text{s}$
- added 19τ to current pulse sequence and halved τ
- many missing lags

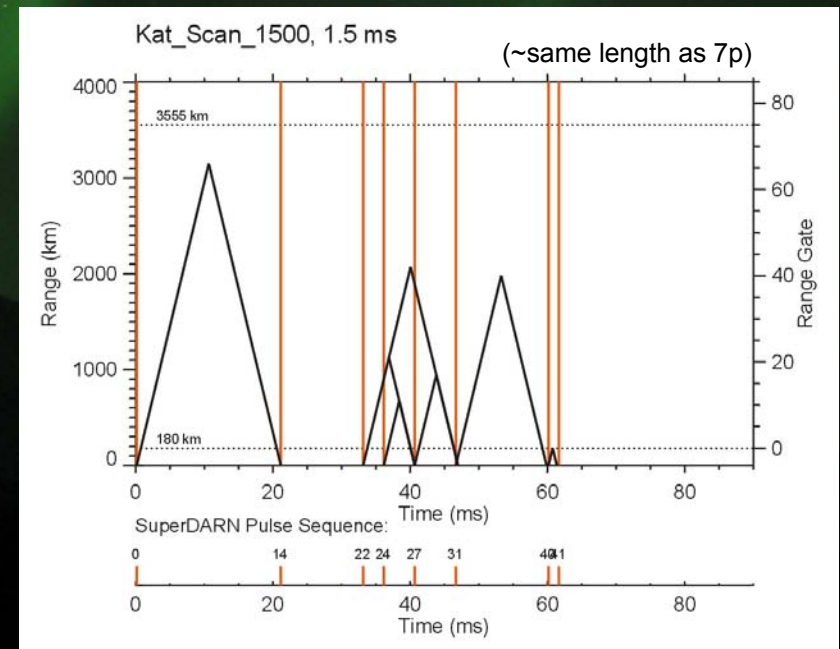


[0, 14, 22, 24, 27, 31, 42, 43]

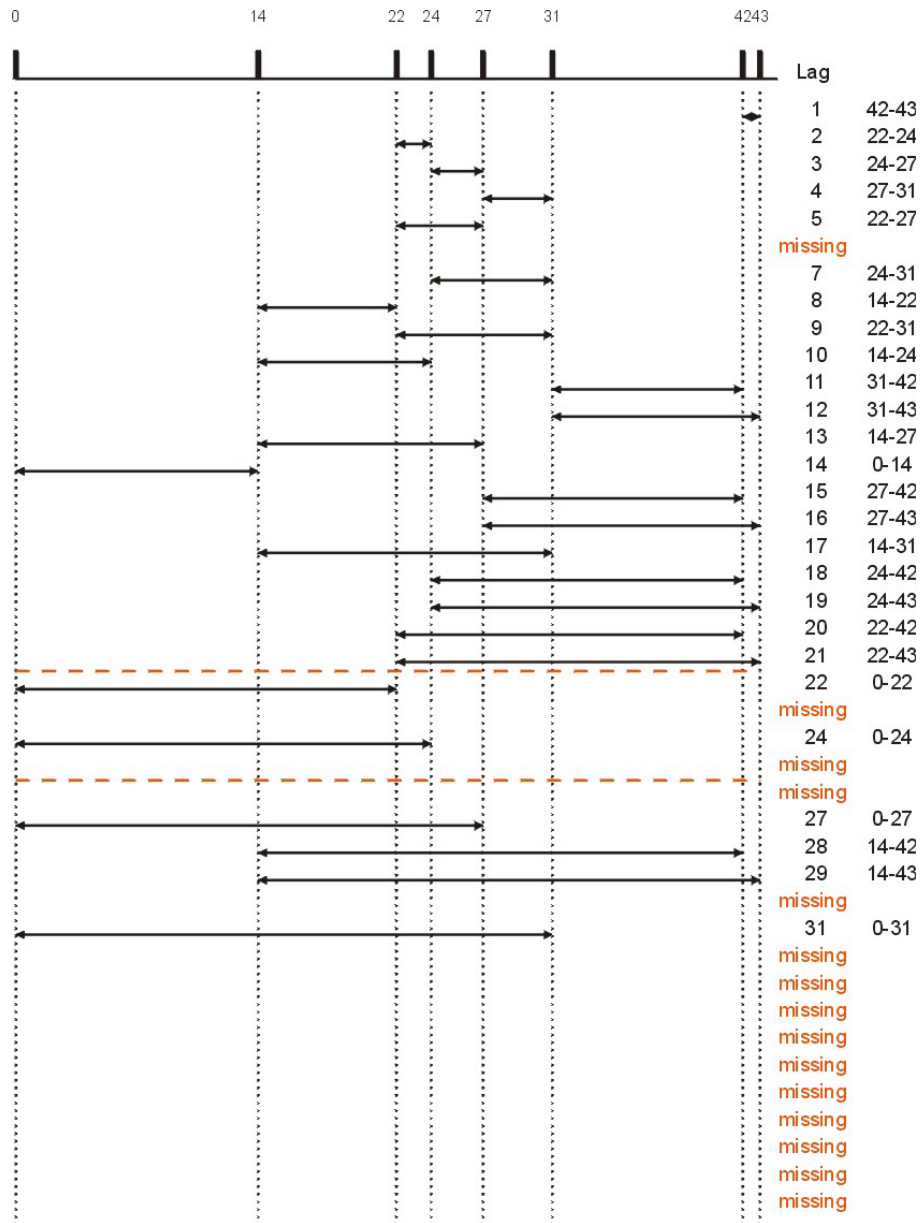


'kat_scan 1500'

- 8 pulses, $\tau = 1500 \mu\text{s}$
- lag 1 separated from rest of sequence
- except for 6τ , missing lags behaviour nearly identical to current 7-pulse sequence

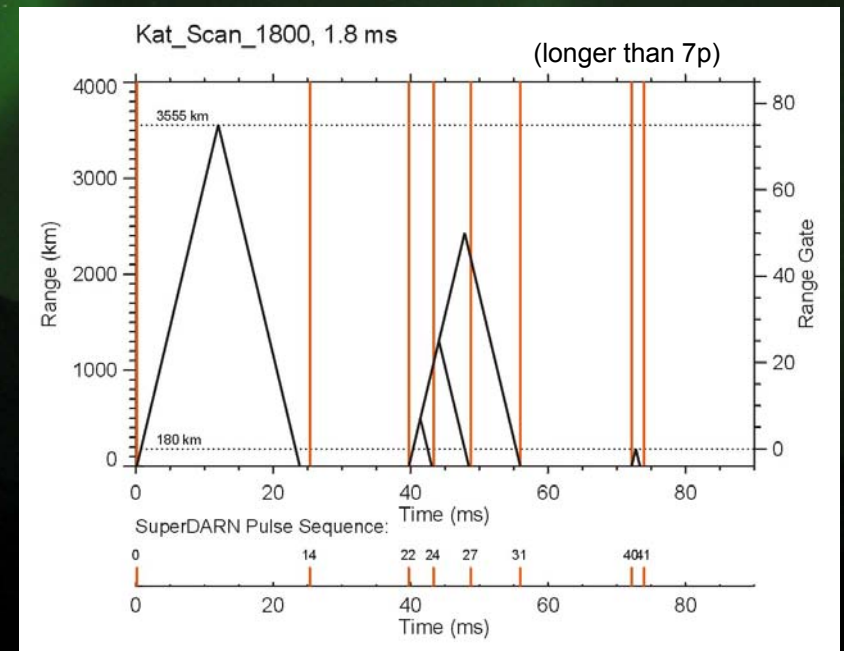


[0, 14, 22, 24, 27, 31, 42, 43]

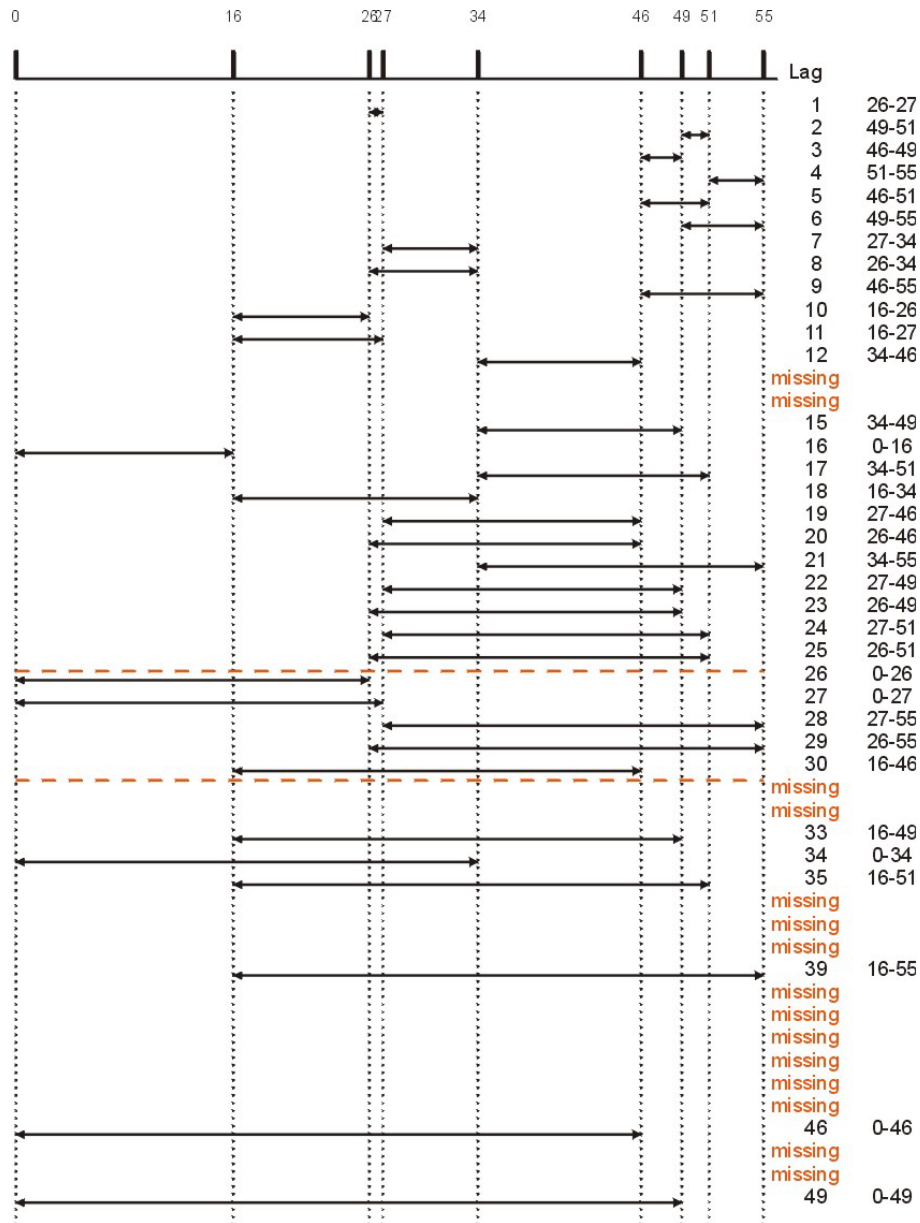


'kat_scan 1800'

- 8 pulses, $\tau = 1800 \mu s$
- lag 0 determination possible at all ranges

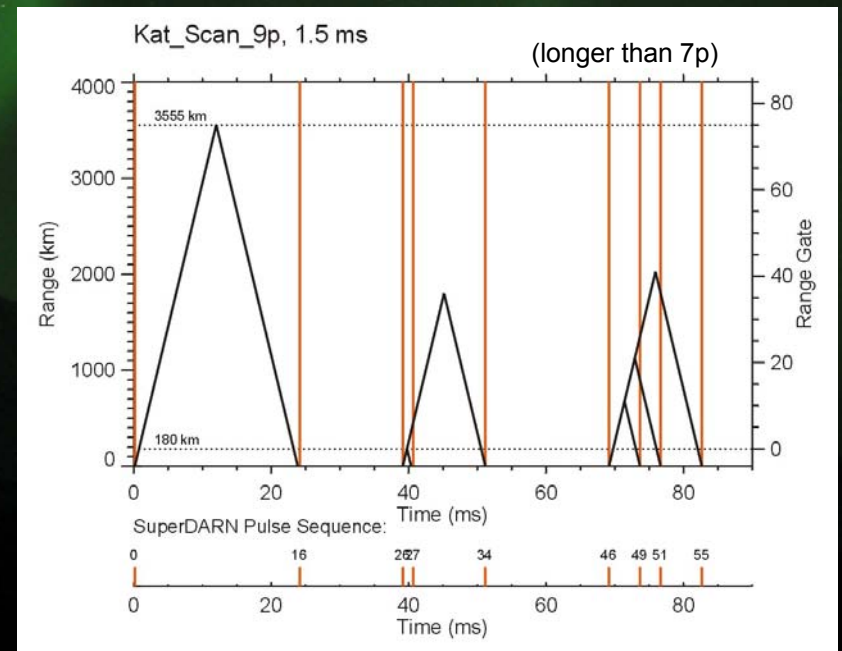


[0, 16, 26, 27, 34, 46, 49, 51, 55]



kat_scan_9p

- 9 pulses, $\tau = 1500 \mu\text{s}$
- lag 0 determination possible at all ranges
- longer pulse train; fewer averages



Pulse Sequence Tests

The Data ...

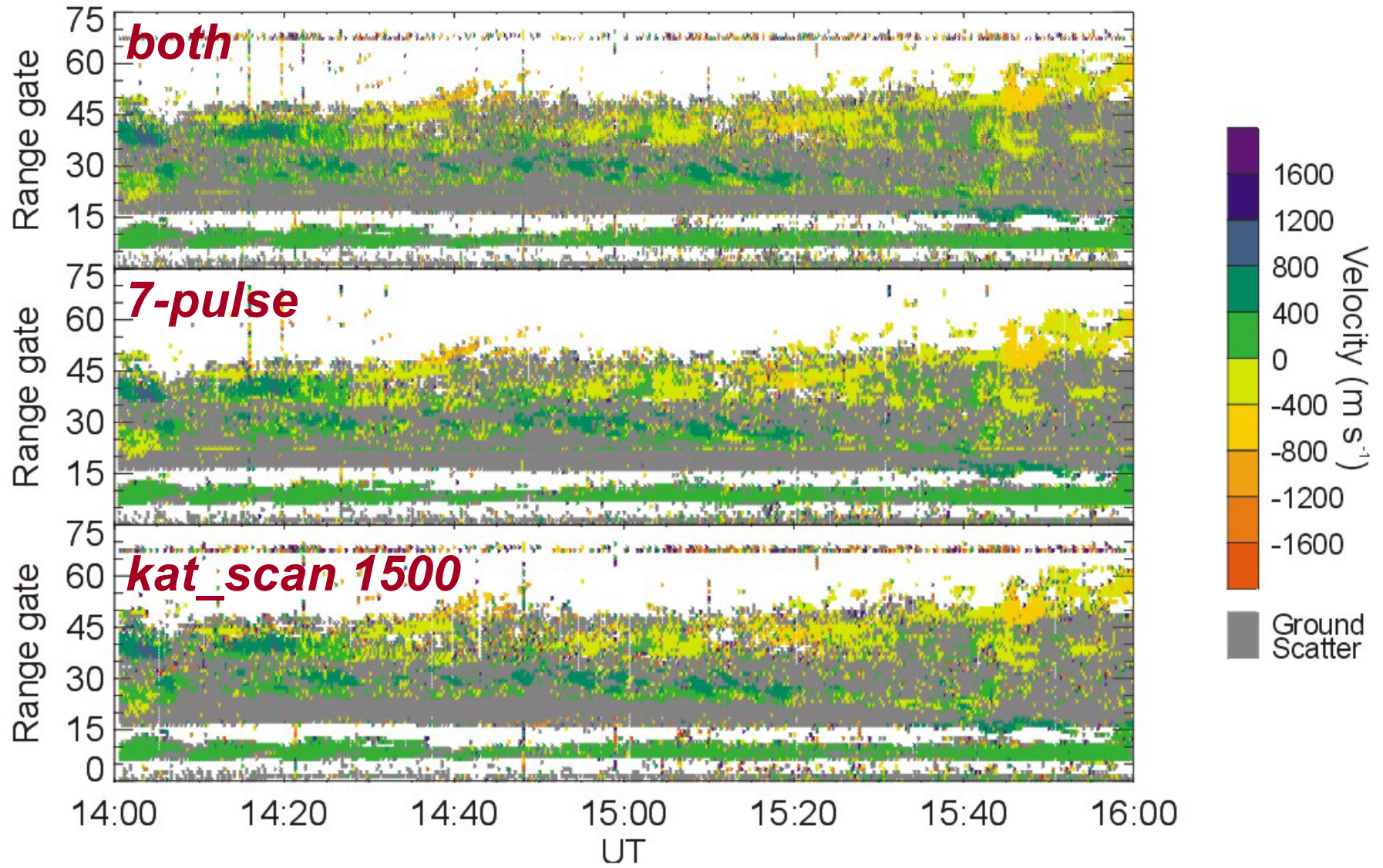


SUPERDARN PARAMETER PLOT

Pykkvibaer: vel

30 Oct 2002 (303)

unknown scan mode (-6406)



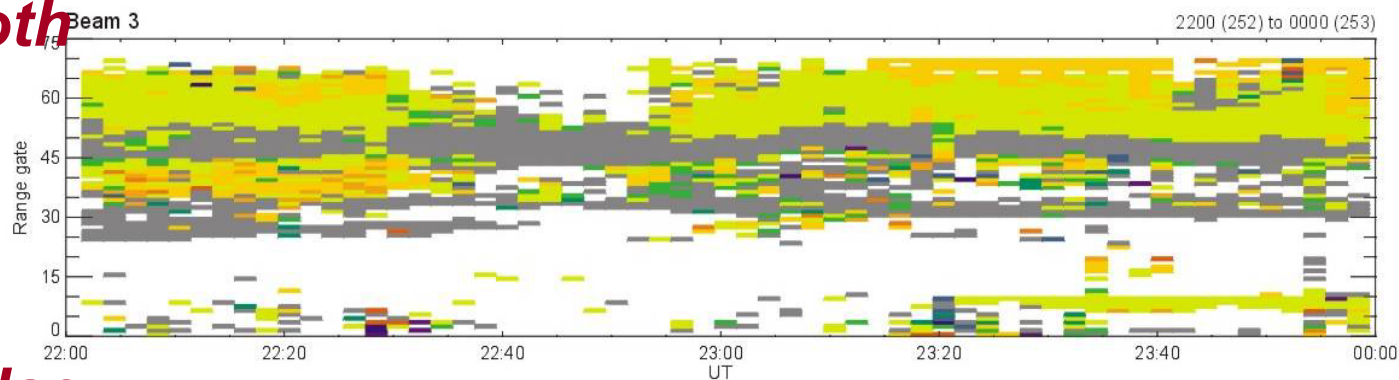
SUPERDARN PARAMETER PLOT

Prince George: vel

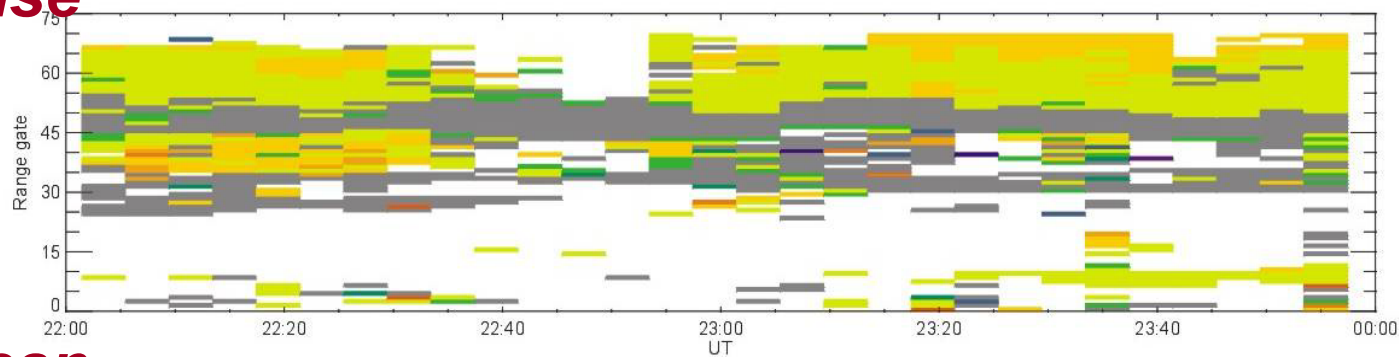
9 Sep 2002⁽²⁵²⁾

unknown scan mode (-3111)

both

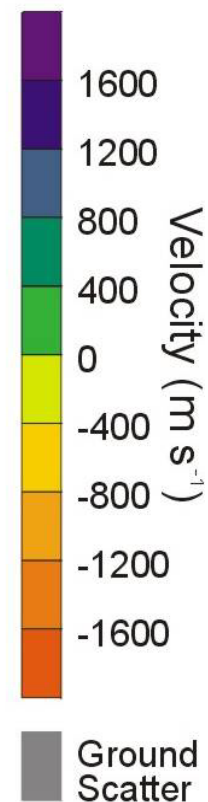
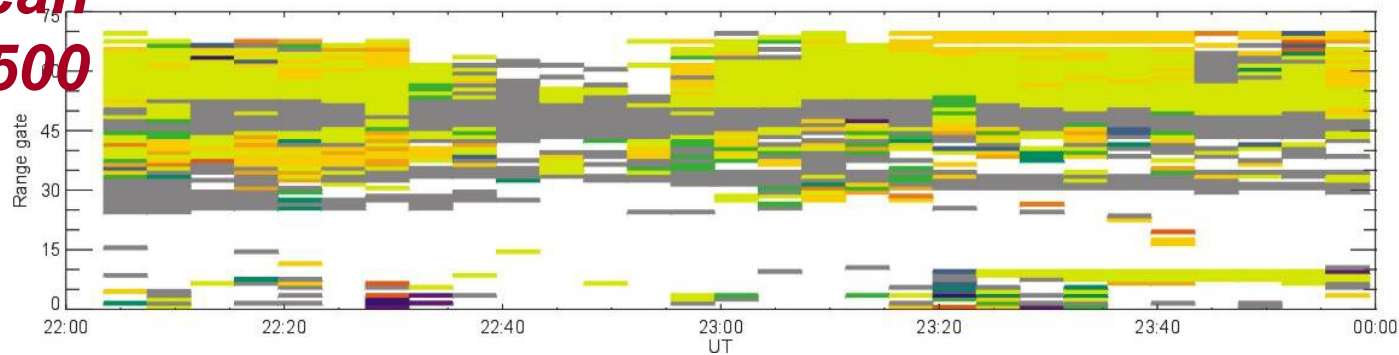


7-pulse



kat_scan

1500



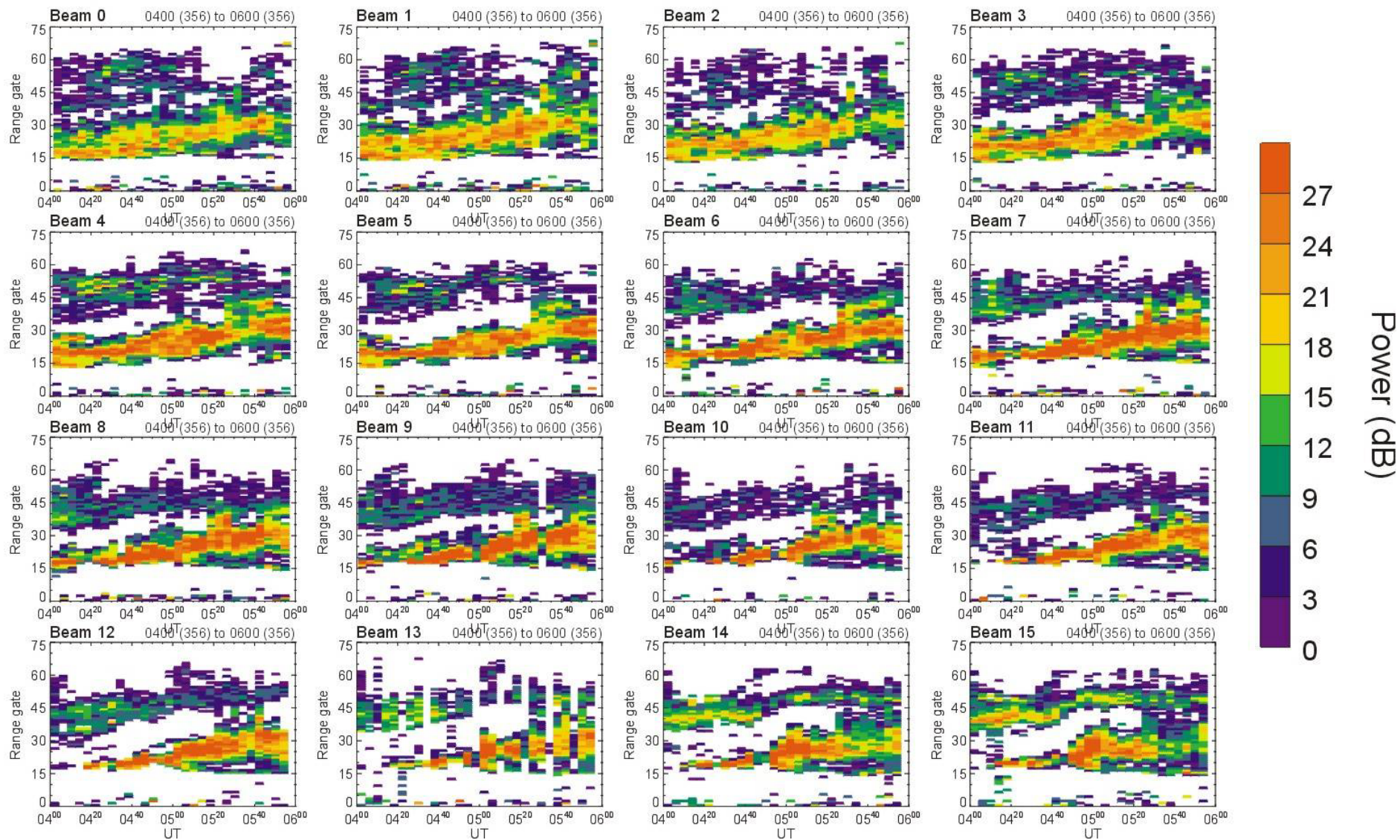
SUPERDARN PARAMETER PLOT

Kapuskasing: pwr_l

7-pulse

22 Dec 2002

unknown scan mode (-155)



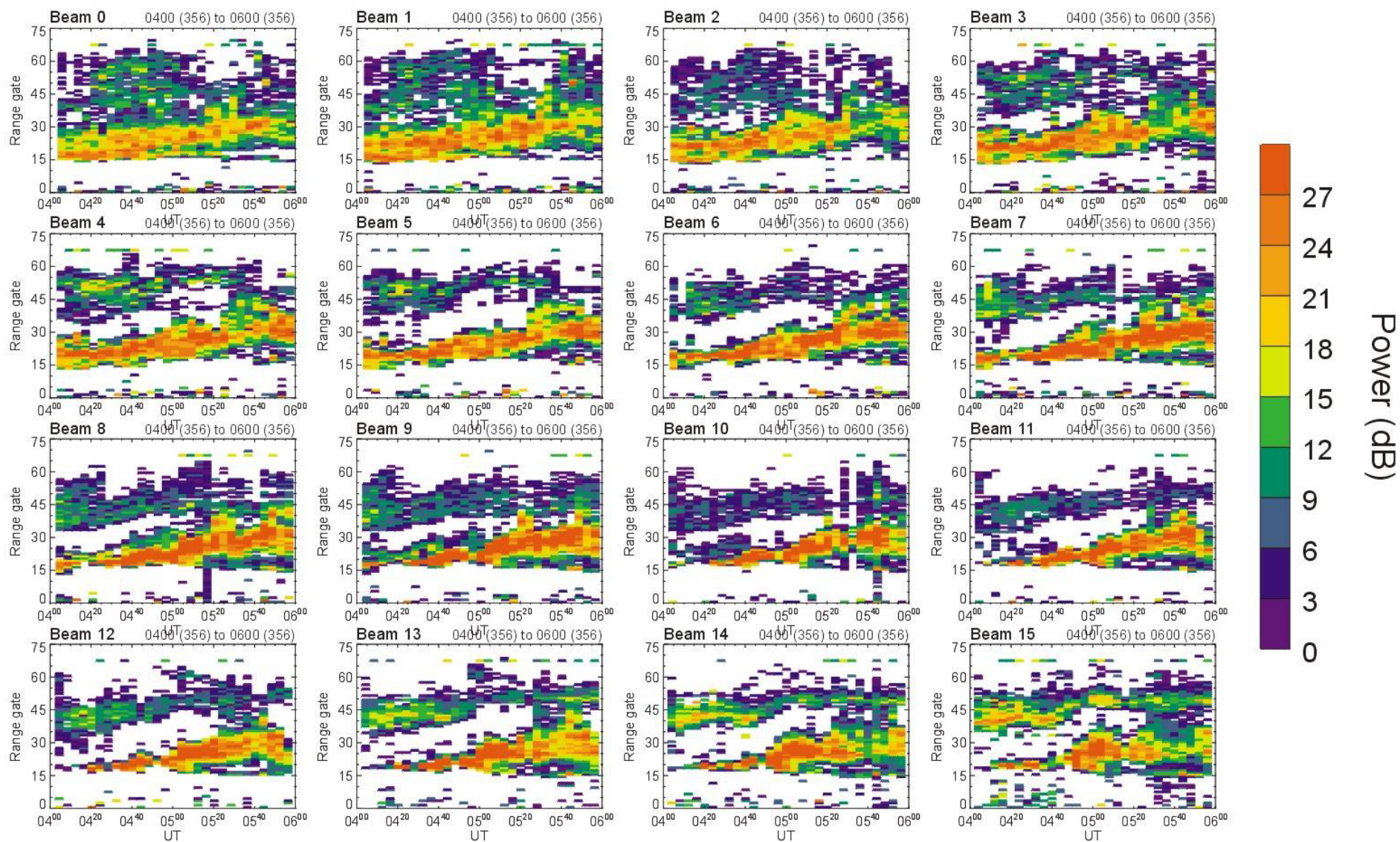
SUPERDARN PARAMETER PLOT

Kapuskasing: pwr_l

kat_scan 1500

22 Dec 2002

unknown scan mode (-155)



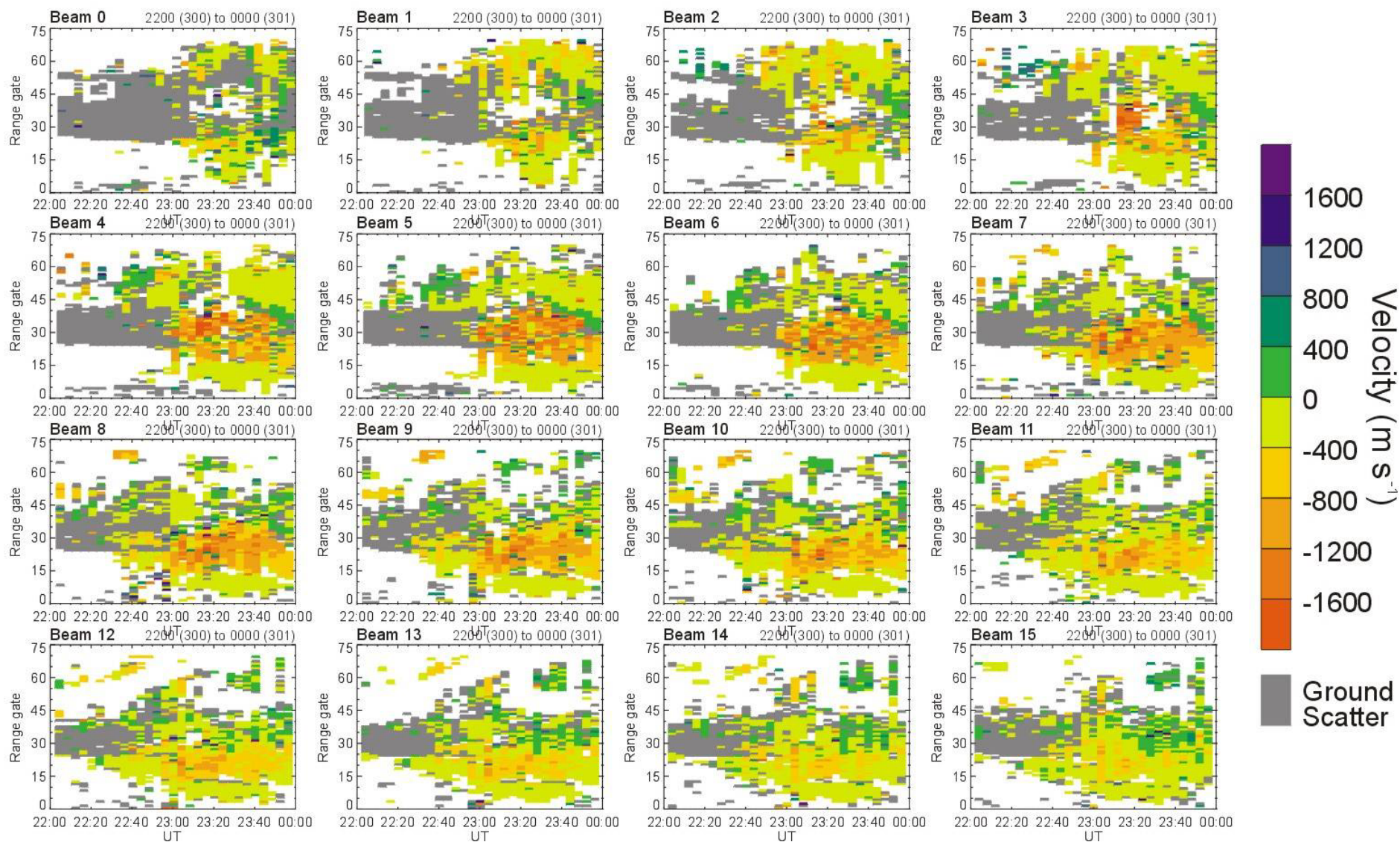
SUPERDARN PARAMETER PLOT

Prince George: vel

7-pulse

27 Oct 2002

unknown scan mode (-3111)



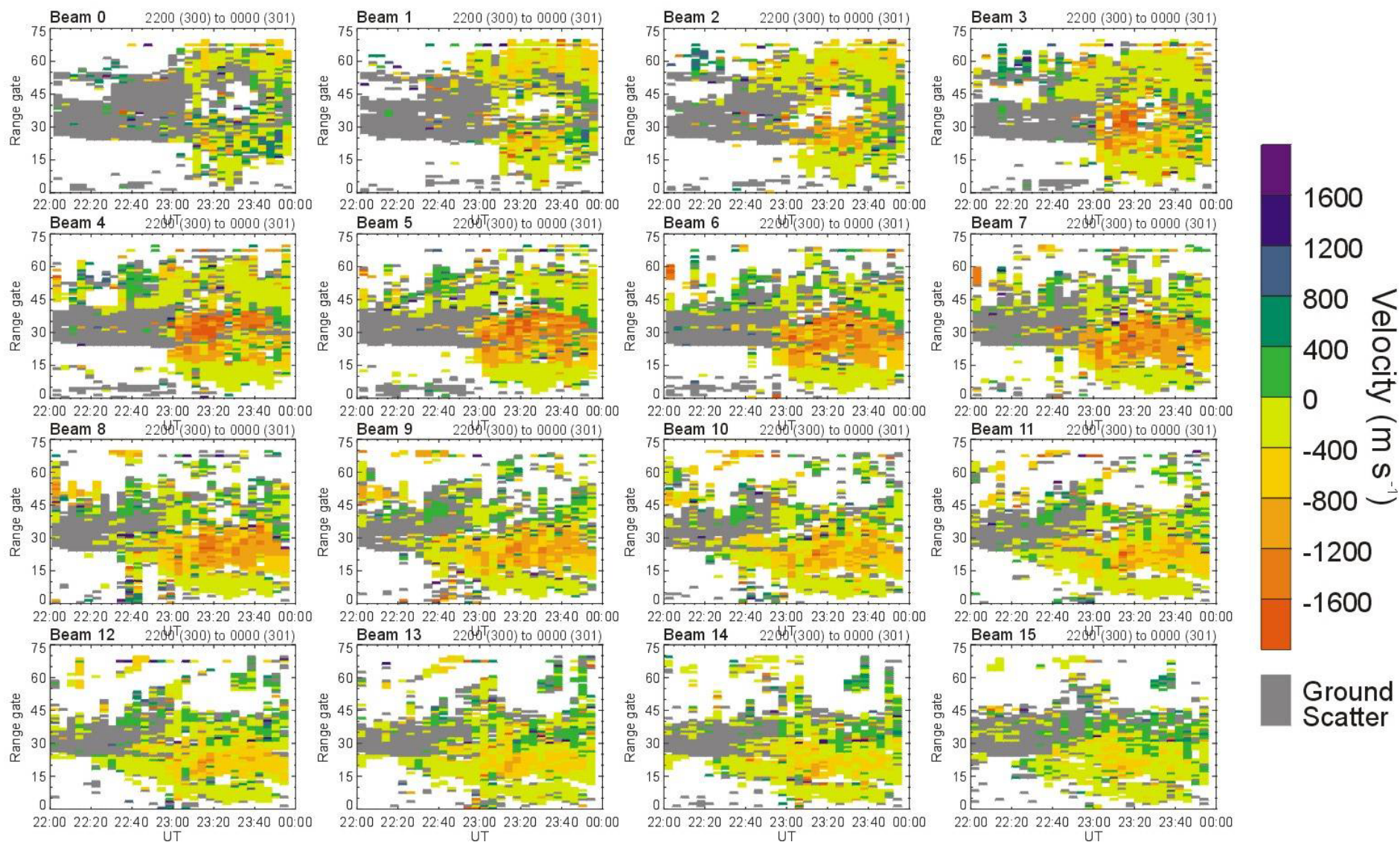
SUPERDARN PARAMETER PLOT

Prince George: vel

kat_scan 1500

27 Oct 2002 (300)

unknown scan mode (-3111)

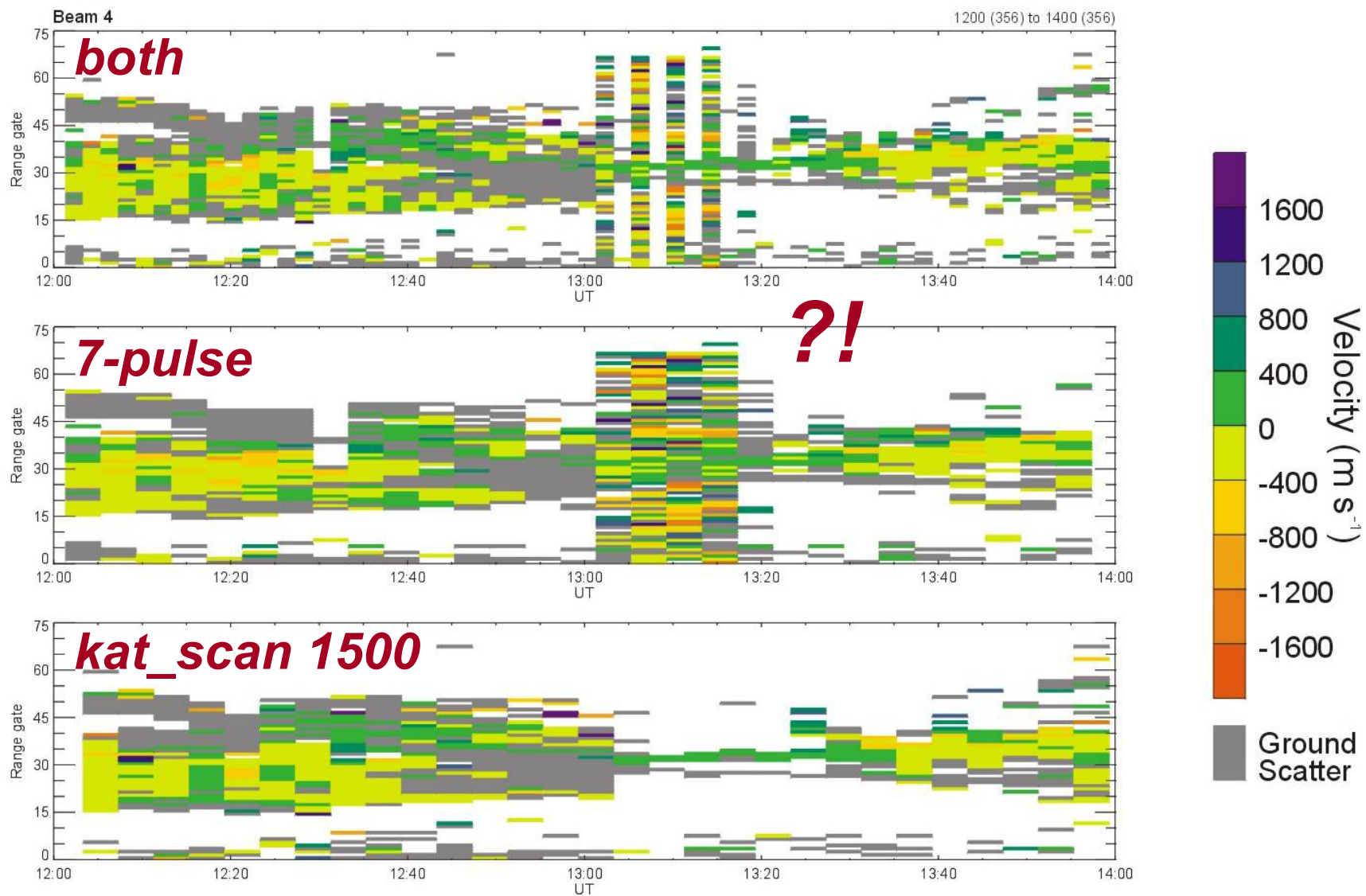


SUPERDARN PARAMETER PLOT

Kapuskasing: vel

22 Dec 2002 (1355)

unknown scan mode (-155)



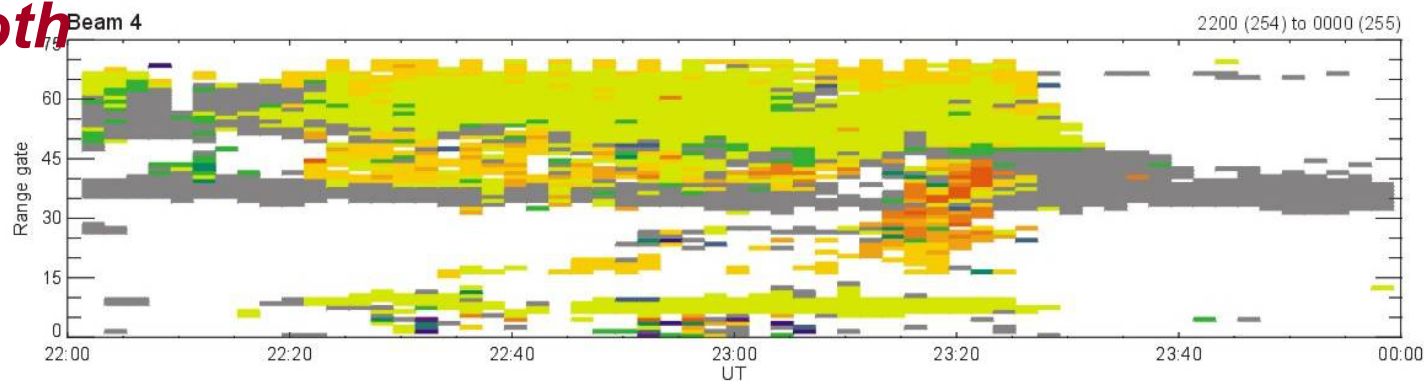
SUPERDARN PARAMETER PLOT

Prince George: vel

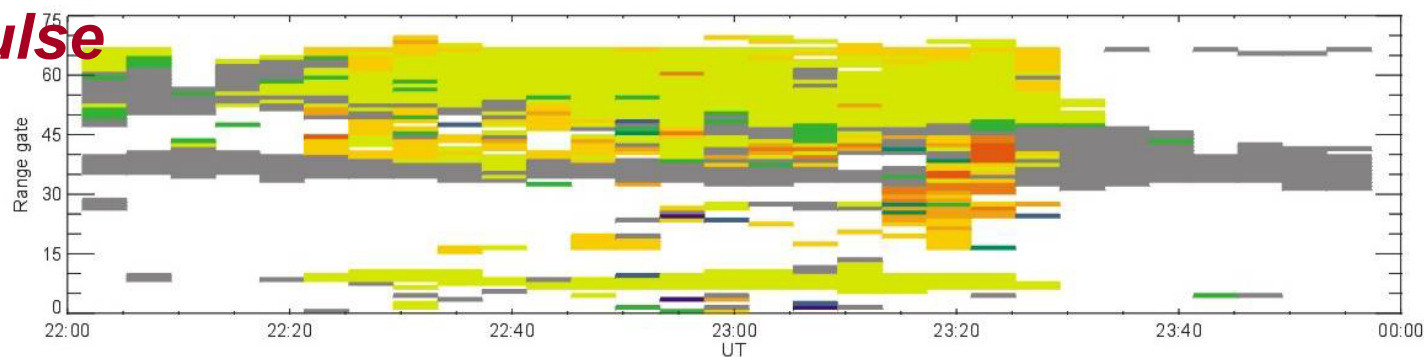
11 Sep 2002 (1254)

unknown scan mode (-3112)

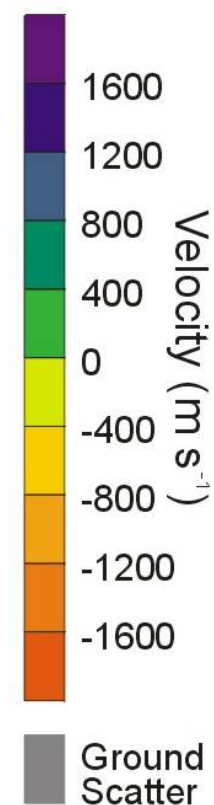
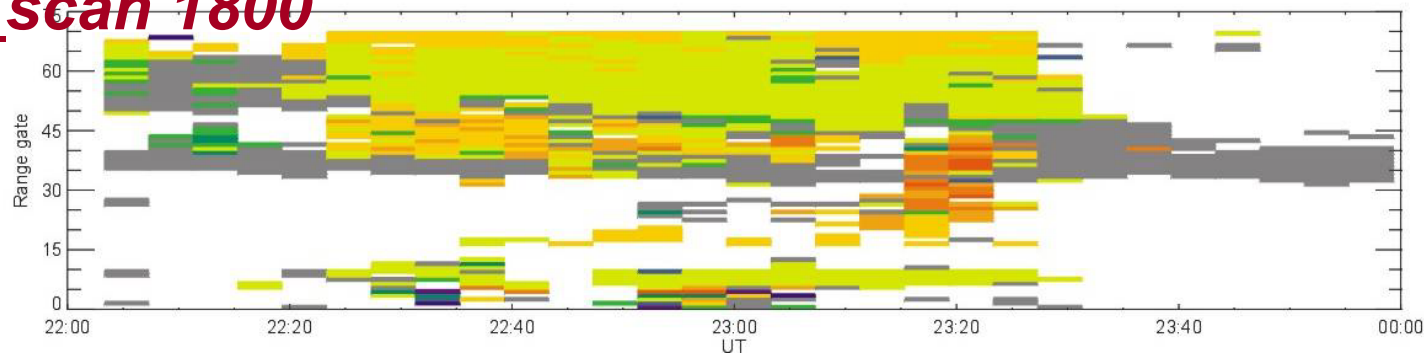
both



7-pulse



kat_scan 1800

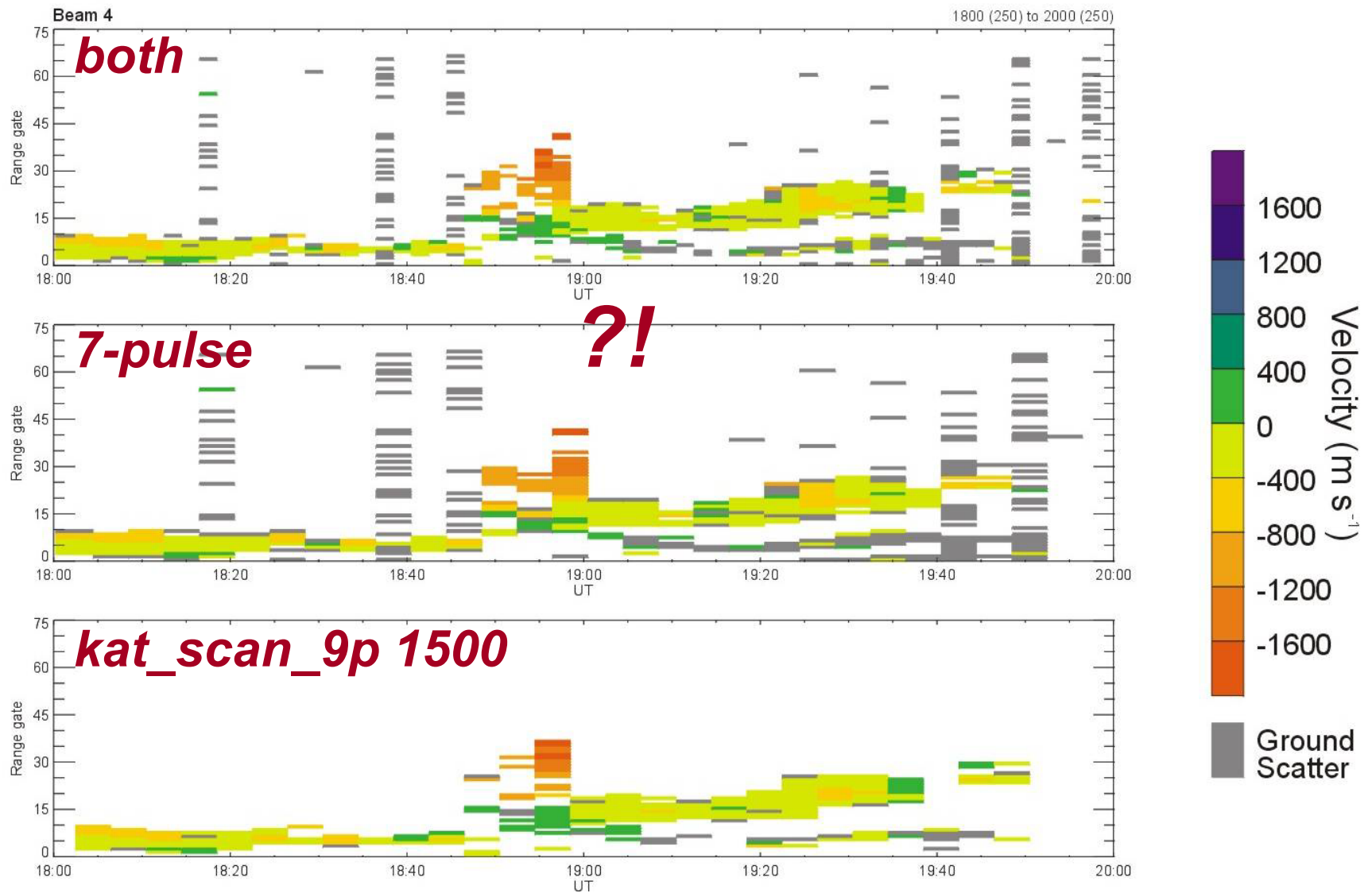


SUPERDARN PARAMETER PLOT

Saskatoon: vel

7 Sep 2002⁽²⁵⁰⁾

unknown scan mode (-3113)

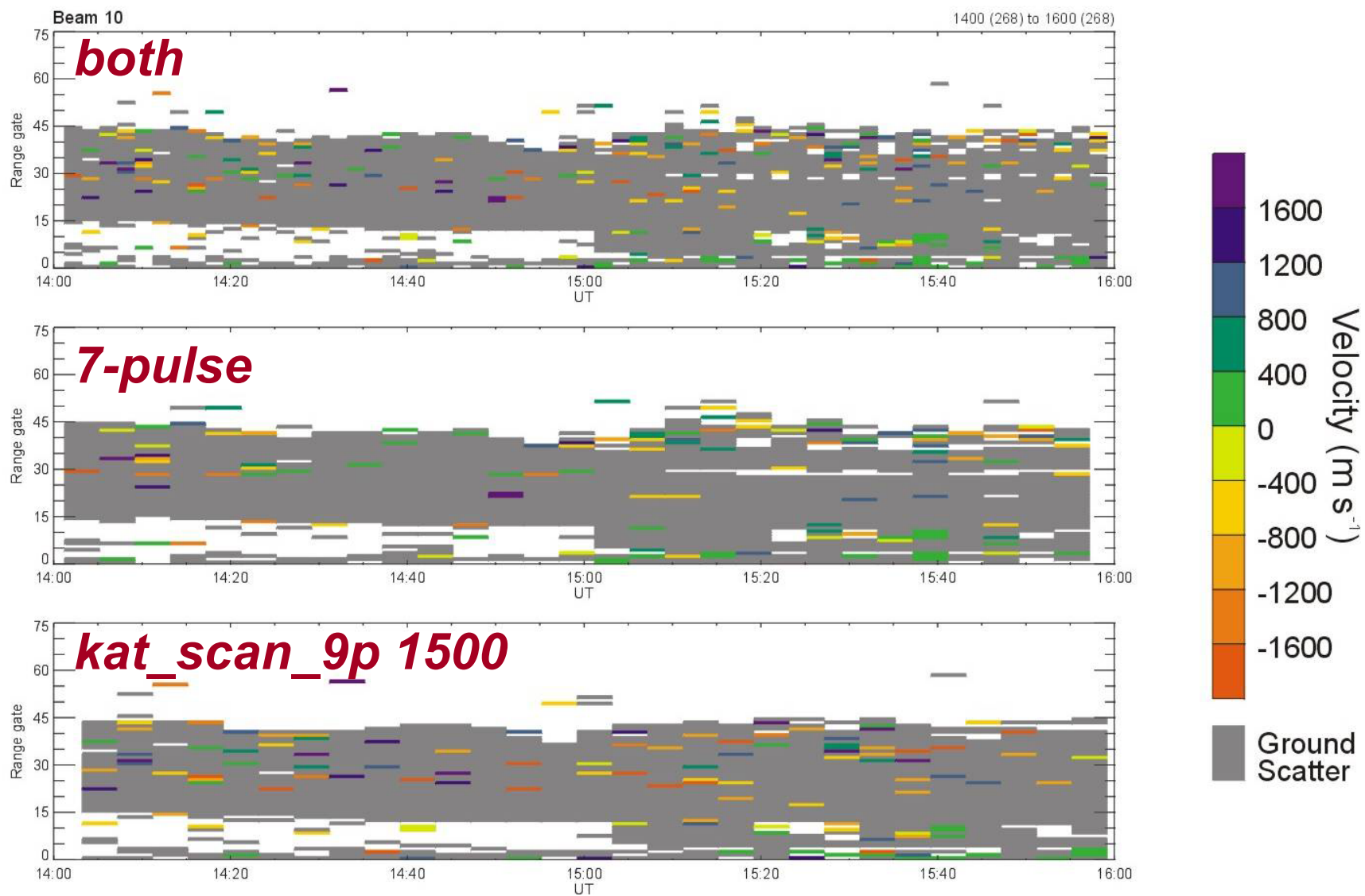


SUPERDARN PARAMETER PLOT

Saskatoon: vel

25 Sep 2002 (1255)

unknown scan mode (-3113)



Pulse Sequence Tests Statistics ...



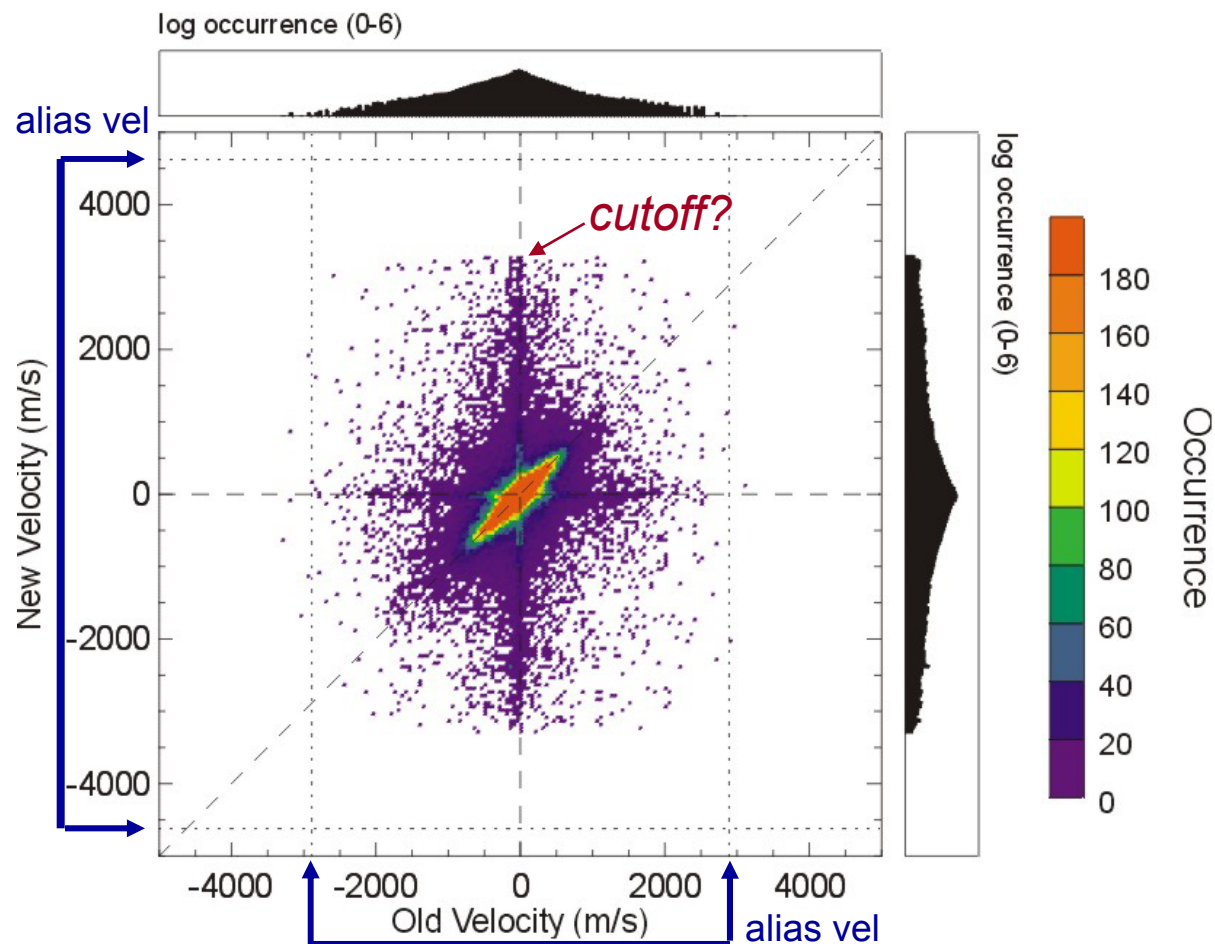
Pulse Sequence Statistics

- CUTLASS:
 - camp beam 5*, alternating pseq's
- All other SD radars:
 - interleaved full scans, alternating pseq's
- Data Selection Criteria:
 - same beam in successive scans
 - ionospheric scatter in both samples
 - 'qflag' good in both samples

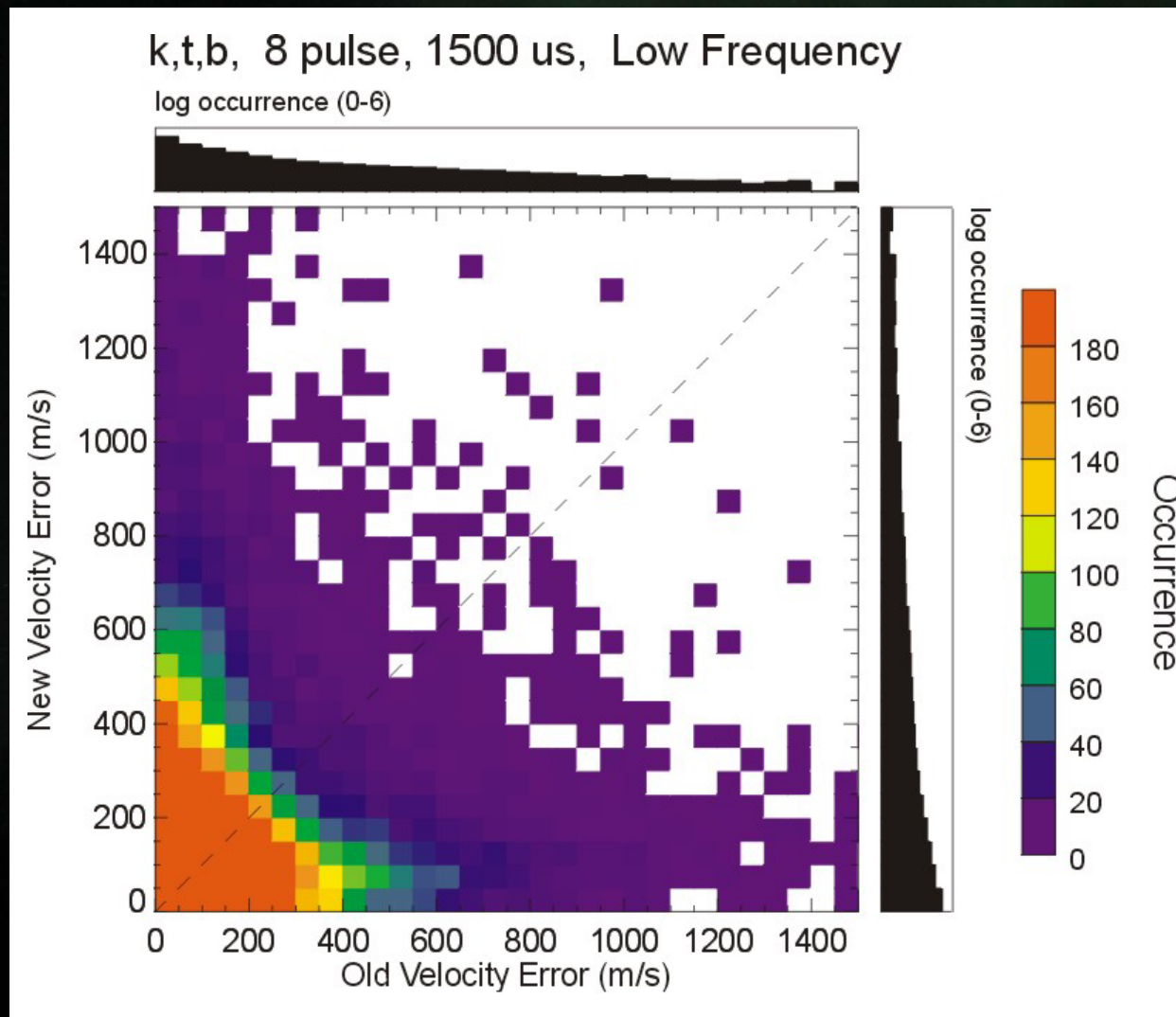


Old vs. New Velocity

k,t,b, 8 pulse, 1500 us, Low Frequency

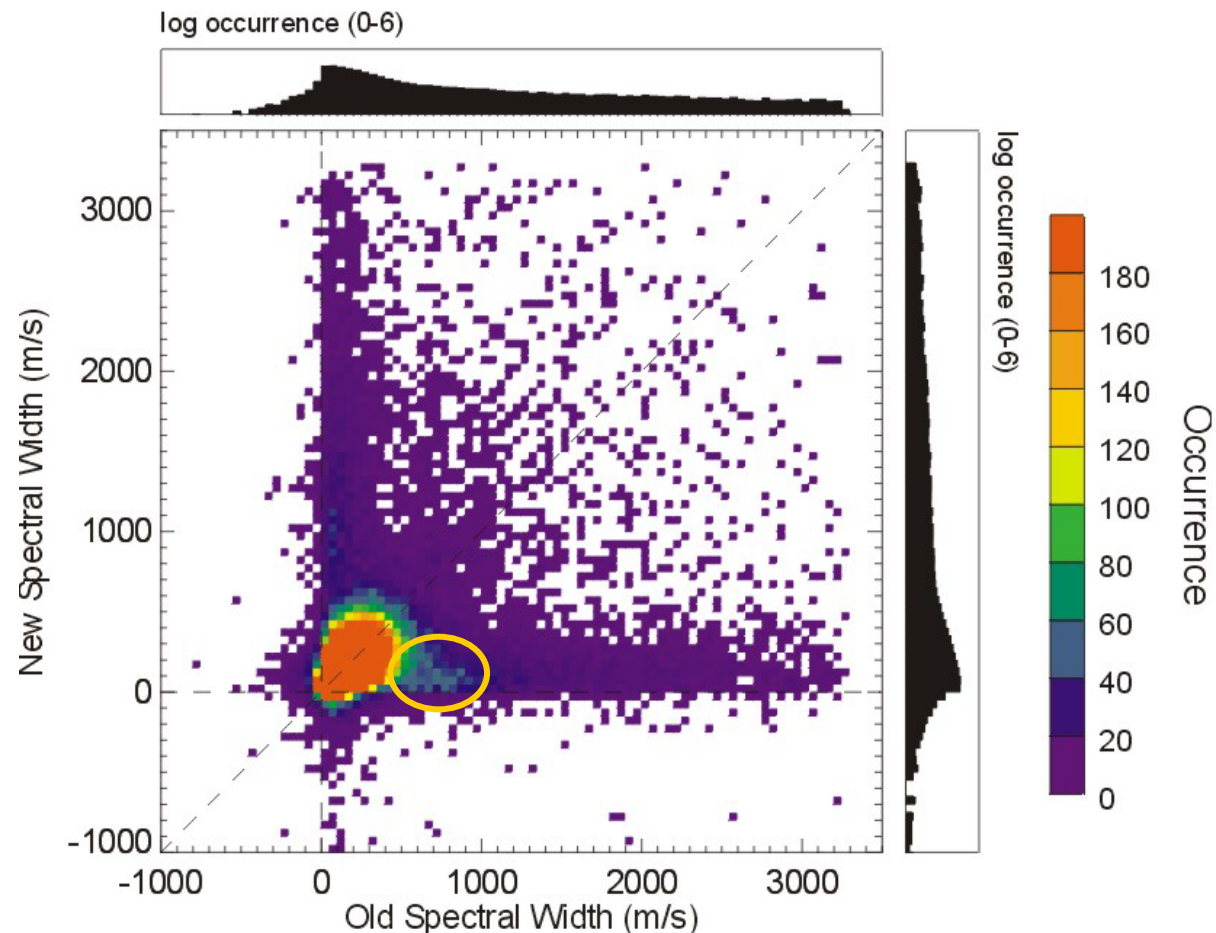


Old vs. New Velocity Error

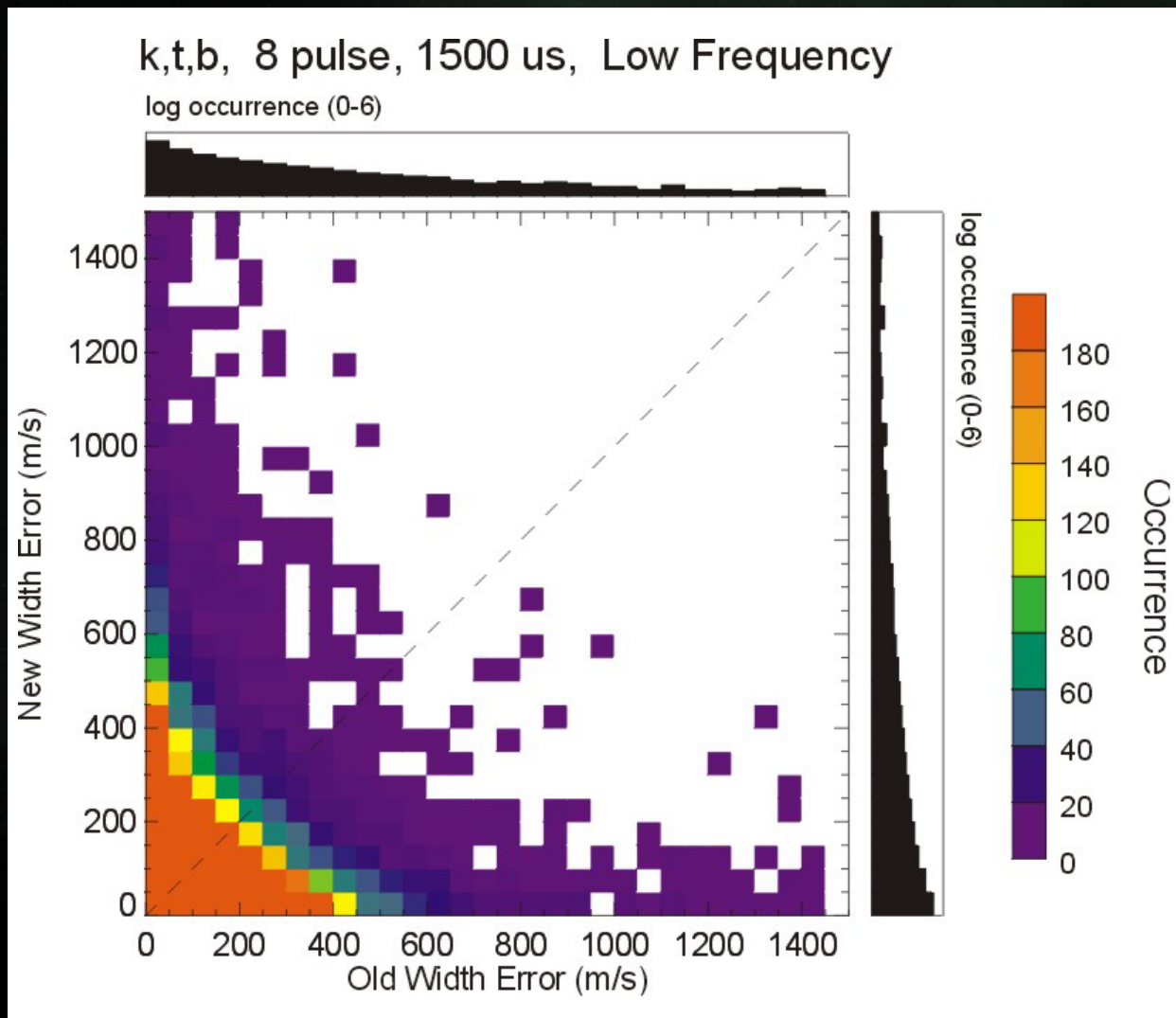


Old vs. New Spectral Width

k,t,b, 8 pulse, 1500 us, Low Frequency

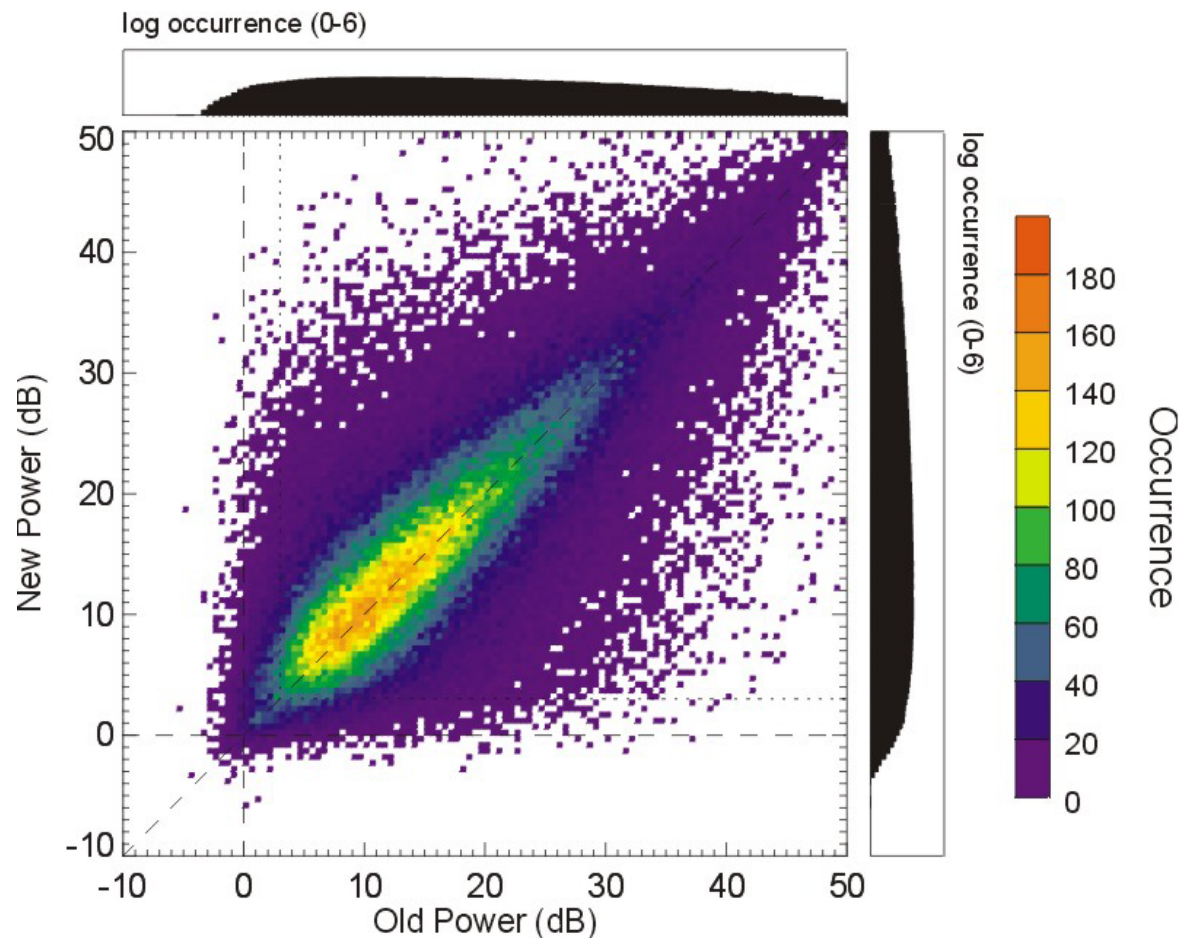


Old vs. New Width Error

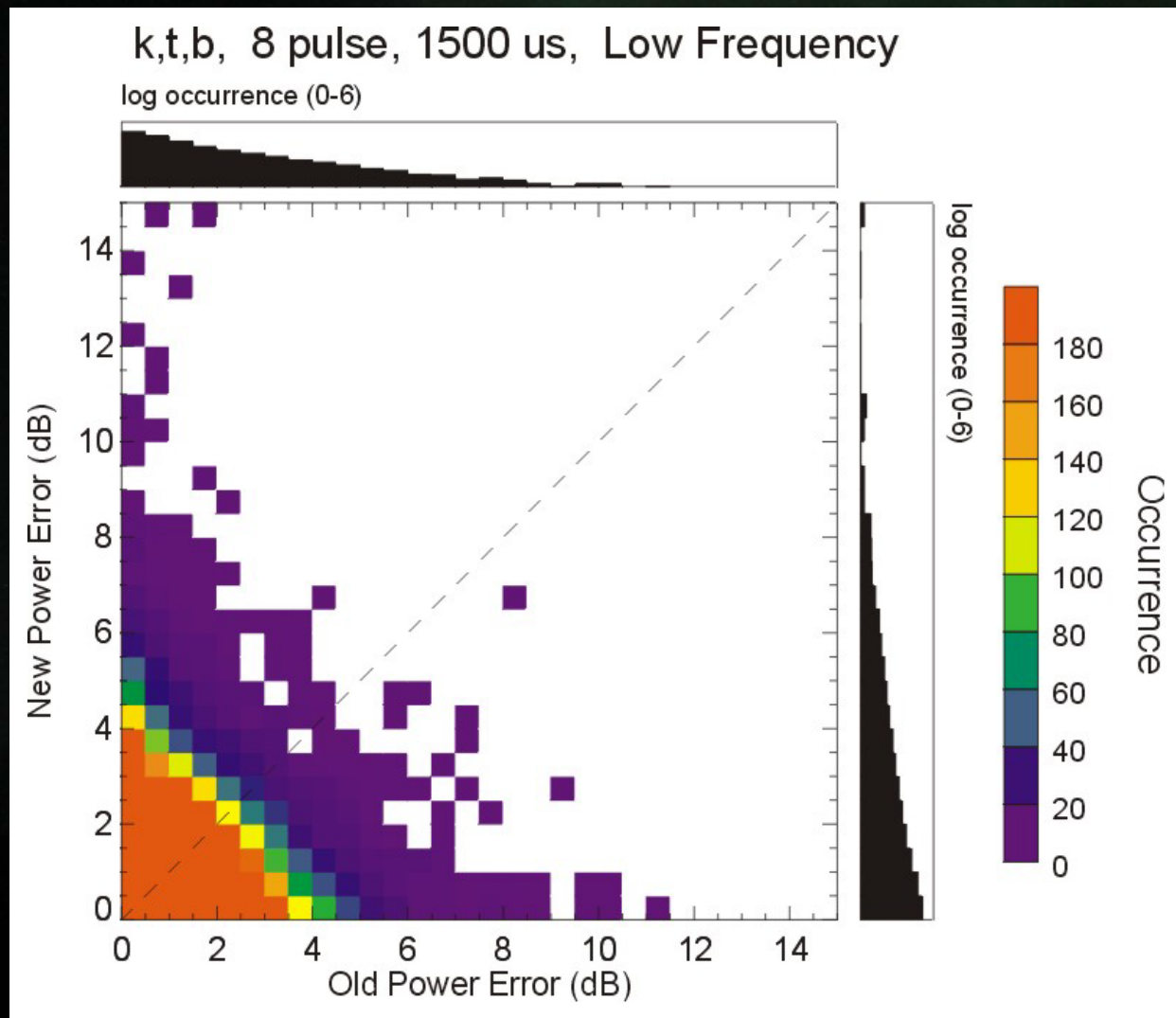


Old vs. New Power

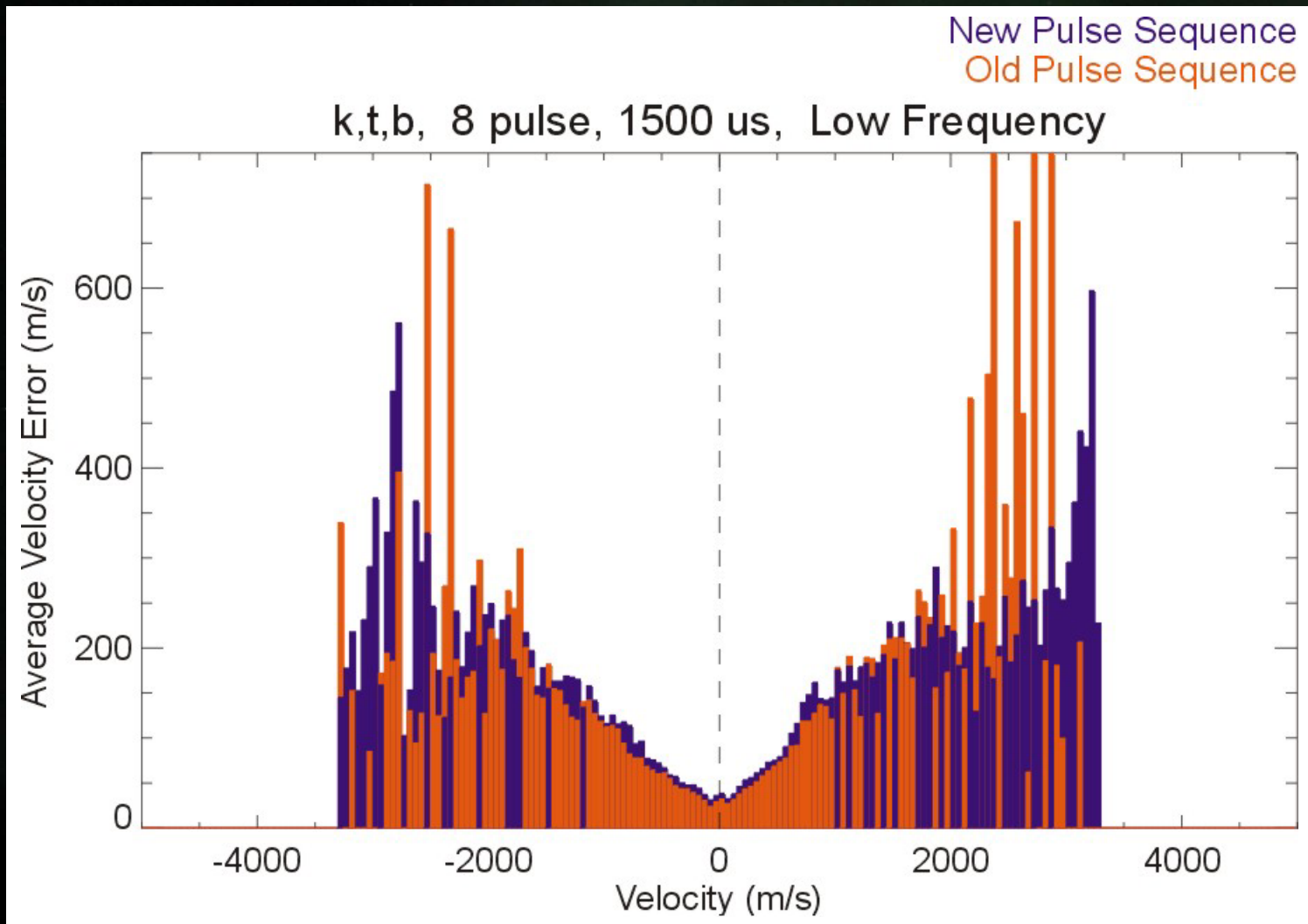
k,t,b, 8 pulse, 1500 us, Low Frequency



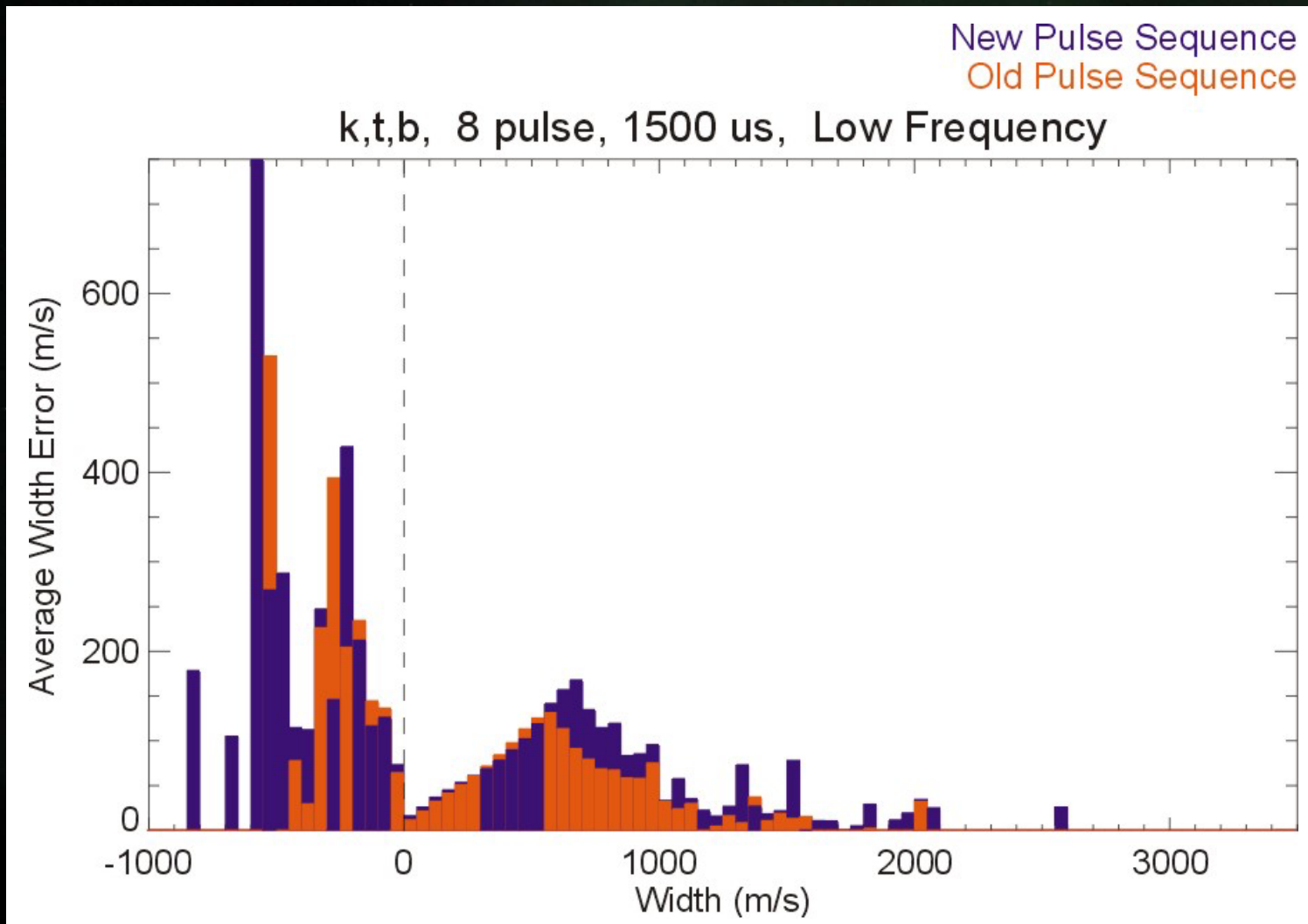
Old vs. New Power Error



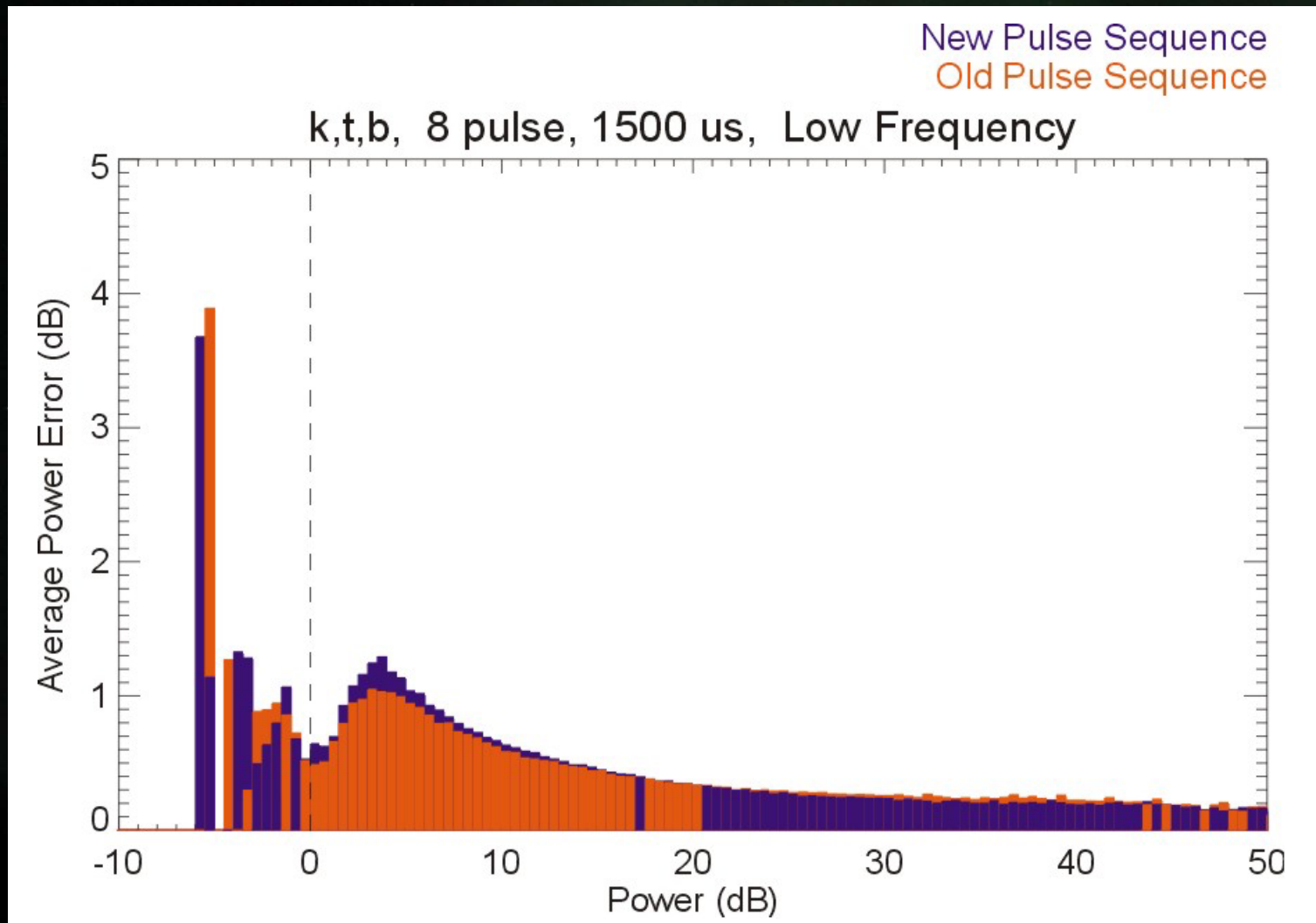
Average Velocity Error



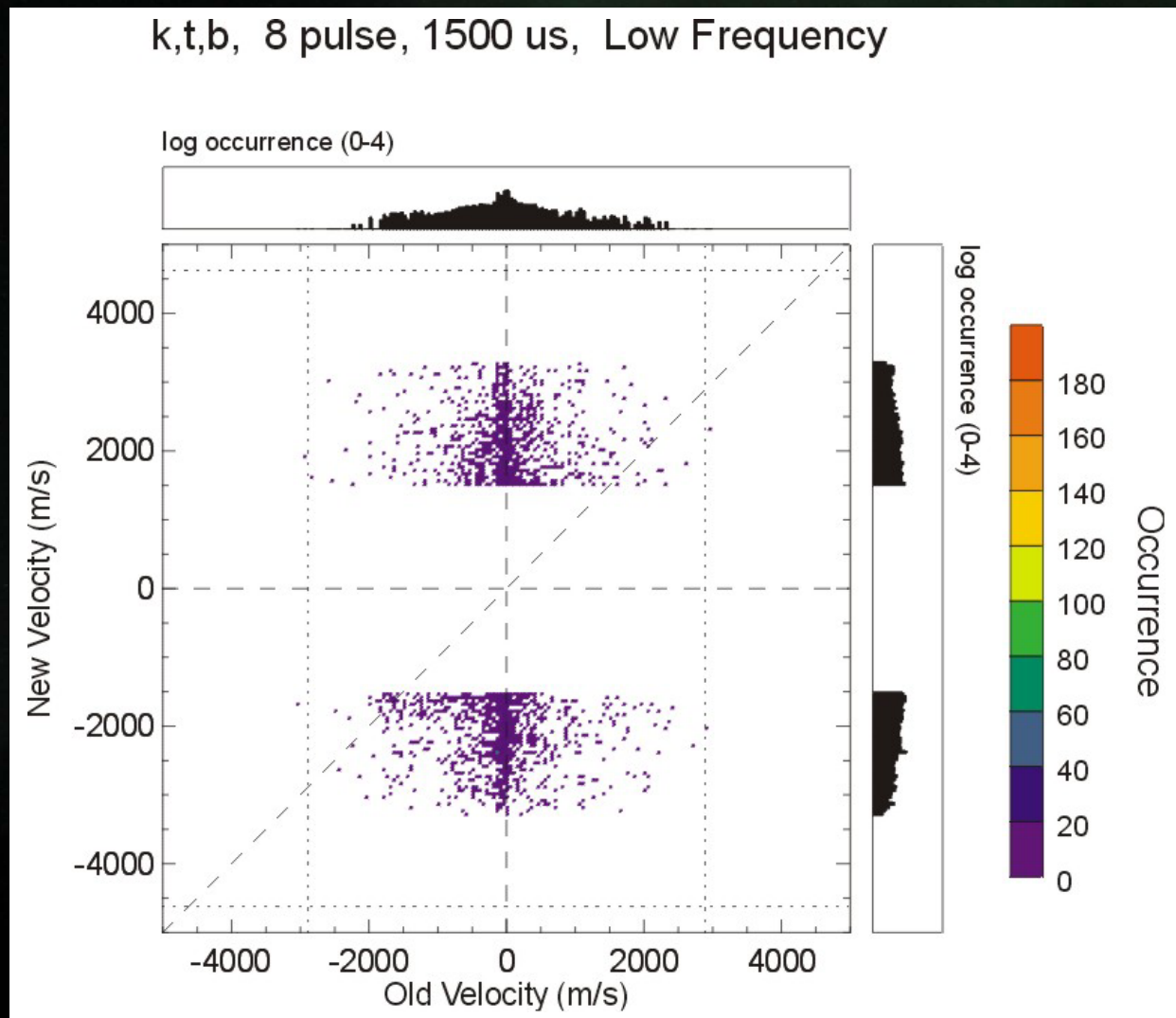
Average Width Error



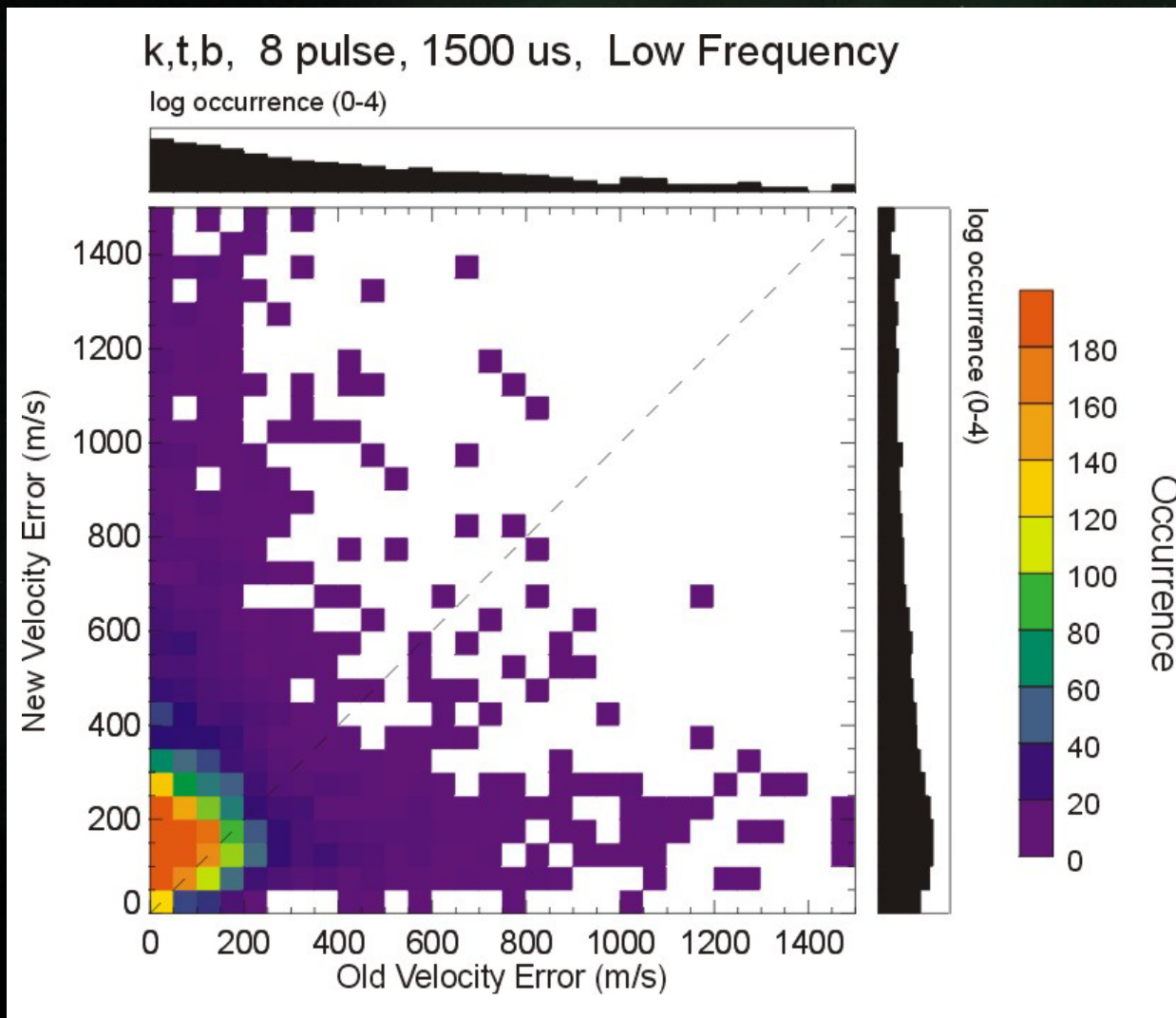
Average Power Error



Old vs. New Velocity - Cutoff



Old vs. New Velocity Error - Cutoff



FITACF Summary

- FITACF cleverly determines mean velocity, power, and width of spectrum.
- Current pulse sequence works well, but there is always room for improvement.



Conclusions

- Data examples show clear differences between pulse sequences:
 - effect of bad lags
 - persistent differences b/w fitted parameters
- Higher velocities measured by new pulse sequences.
- Better determination of ACFs with more samples
 - to me seems to be more important than velocity aliasing (but mostly moderate velocities measured during these tests ~ several hundred m/s flows)



Future Work

- Test for high flows
 - e.g., þykkvibær/Stokkseyri zonal beams.
- Stereo test:
 - measurements from same region.
 - possible stereo badlags problems?
- Statistics for only high flow events.
- % ground/iono scatter.
- Case study of ACFs of pseqs.
- Re-evaluate errors, ground scatter definition, etc.

